

The logo features the word "DIVER" in a bold, black, sans-serif font. Below it is a dark blue shield with a white number "6" in the center. The shield is outlined with a thick green border. The entire logo is set against a background of blue water with light rays filtering down from the surface.

**DIVER**

*Diving Safety Evolved*

User Manual

4.0



## TABLE OF CONTENTS

|  |           |
|--|-----------|
| <b>SECTION 1: INTRODUCTION .....</b>   | <b>6</b>  |
| <b>WELCOME .....</b>   | <b>6</b>  |
| <b>INITIAL CHECKING OF THE DIVER6 SYSTEM ON ARRIVAL.....</b>                       | <b>6</b>  |
| CHECKING CONTENTS .....  | 7         |
| <b>DISCLAIMER.....</b>   | <b>8</b>  |
| <b>WARRANTY .....</b>  | <b>9</b>  |
| <i>Warranty Exclusions/Limitations.....</i>  | <i>9</i>  |
| <i>Procedure for Making a Warranty Claim.....</i>                                  | <i>9</i>  |
| <i>Warranty Contact Information.....</i>   | <i>10</i> |
| <b>SECTION 2: SYSTEM OVERVIEW .....</b>  | <b>11</b> |
| <b>HOW DOES IT WORK? .....</b>   | <b>11</b> |
| EXPECTED RANGE.....  | 12        |
| LIMITATIONS ON RANGE.....  | 12        |
| <i>The effect of thermoclines.....</i>   | <i>12</i> |
| <i>Environmental effects.....</i>  | <i>13</i> |
| DIVER6 SYSTEM SPECIFICATIONS.....  | 14        |
| TOPSIDE EQUIPMENT .....  | 14        |
| <i>Topside Modem.....</i>  | <i>14</i> |
| <i>Topside Battery Unit.....</i>   | <i>15</i> |
| <i>Topside Monitoring Computer.....</i>  | <i>15</i> |
| DIVER EQUIPMENT .....  | 16        |
| <i>Diver Modem.....</i>  | <i>16</i> |
| <b>SECTION 3: GETTING STARTED .....</b>  | <b>17</b> |
| GETTING STARTED.....   | 17        |
| DIVER .....  | 17        |
| <i>Attaching the Diver Beacon.....</i>   | <i>17</i> |
| INTERFERENCE WITH OCEAN TECHNOLOGY SYSTEMS (OTS) THROUGH WATER COMMUNICATIONS..... | 18        |
| TOPSIDE MODEM .....  | 19        |
| TOPSIDE MODEM MOUNT INSTRUCTIONS .....   | 20        |
| <b>SOFTWARE .....</b>  | <b>21</b> |
| DEFAULT SETUP.....   | 21        |
| <b>GETTING STARTED GUIDE SUMMARY .....</b>   | <b>22</b> |
| DIVER .....  | 22        |
| <i>Pre-deployment.....</i>   | <i>22</i> |
| <i>Deployment.....</i>   | <i>22</i> |
| TOPSIDE MODEM .....  | 24        |
| <i>Pre-deployment.....</i>   | <i>24</i> |
| <i>Deployment.....</i>   | <i>24</i> |
| <i>Post-deployment.....</i>  | <i>24</i> |
| SOFTWARE .....   | 25        |
| <i>Pre-deployment.....</i>   | <i>25</i> |
| <i>Deployment.....</i>   | <i>25</i> |
| <i>Post-deployment.....</i>  | <i>25</i> |



**SECTION 4: DIVER6 SYSTEM OPERATION ..... 26**

**INTRODUCTION ..... 26**

**TOPSIDE EQUIPMENT ..... 26**

    TOPSIDE MODEM POSITIONING ..... 26

*Swimming Pool* ..... 26

*Pier / Wharf*..... 28

*Marina*..... 29

*Boat*..... 30

    TOPSIDE EQUIPMENT DEPLOYMENT ACTIONS ..... 32

*Topside Equipment Pre-Deployment Actions* ..... 32

*Topside Equipment Deployment Actions*..... 33

*Topside Equipment Post Deployment Actions*..... 33

    DIVER EQUIPMENT ..... 34

*Diver Equipment Pre-Deployment Actions* ..... 34

*Diver Equipment Deployment Actions*..... 34

*Diver Equipment Post-Deployment Actions* ..... 35

**SECTION 5: SOFTWARE ..... 36**

    SOFTWARE SUMMARY ..... 36

    SYSTEM REQUIREMENTS ..... 36

    OPTIONAL HARDWARE ..... 36

    USING THE SOFTWARE ..... 37

    SOFTWARE UPDATE ..... 38

    REGISTRATION..... 39

    DIVE MASTER LOGIN SCREEN ..... 39

*Logging In* ..... 40

*Manage Dive Masters* ..... 41

*Choose Photo*..... 42

    MAIN MENU ..... 43

*Manage Divers*..... 44

*Dive Plan* ..... 46

*Dive Operations*..... 47

*Communications*..... 49

*Modem ID Setup*..... 50

*Global Alarms* ..... 51

*Destinations*..... 52

*Switch Dive Master*..... 53

*Diagnostics*..... 53

*Dive Log Maintenance*..... 54

    DIVE MONITORING ..... 55

*Diver Detail*..... 56

*Views and Operations*..... 58

*Control* ..... 59

*Recall*..... 60

*Assist*..... 61

*Mark*..... 62

*Send*..... 63

*Charts*..... 64

*Dive Team*..... 66



|  |           |
|--|-----------|
| ALARMS.....  | 67        |
| TABLES.....  | 68        |
| NOTES .....  | 69        |
| ADDITIONAL FUNCTIONALITY .....                           | 70        |
| <i>Shearwater® Distress</i> .....                        | 70        |
| <i>Shearwater® Send Return Home</i> .....                | 70        |
| <i>Shearwater® Send Assist</i> .....                     | 70        |
| <b>SECTION 6: MAINTENANCE .....</b>                      | <b>71</b> |
| <b>INTRODUCTION .....</b>                                | <b>71</b> |
| ROUTINE MAINTENANCE.....                                 | 71        |
| WEEKLY MAINTENANCE TASKS.....                            | 71        |
| RETURN TO FACTORY ANNUAL MAINTENANCE.....                | 72        |
| <b>SECTION 7: TROUBLESHOOTING .....</b>                  | <b>73</b> |
| <b>CHART MANAGEMENT APPENDIX .....</b>                   | <b>75</b> |
| <b>CHARTS OVERVIEW .....</b>                             | <b>76</b> |
| MAP MOVEMENT .....                                       | 77        |
| MARKER IDENTIFICATION .....                              | 77        |
| DIVER INFORMATION .....                                  | 77        |
| HISTORY AND TRAILS.....                                  | 77        |
| <b>CHART SERVER .....</b>                                | <b>78</b> |
| GATHERING YOUR CHARTS.....                               | 78        |
| LOADING YOUR CHARTS (NOAA ENC).....                      | 78        |
| LOADING YOUR CHARTS (INTERNATIONAL S-63) .....           | 79        |
| <i>Setting up International Charts Tile Server</i> ..... | 79        |
| <b>HARDWARE DEVICE FIRMWARE MAINTENANCE.....</b>         | <b>81</b> |
| DCM .....  | 81        |
| SHEARWATER® DEVICES .....                                | 82        |



## Table Of Figures

|  |    |
|--|----|
| FIGURE 1: SYSTEM COMMUNICATION.....                            | 11 |
| FIGURE 2: THERMOCLINE DIAGRAM .....                            | 12 |
| FIGURE 3: TOPSIDE MODEM .....                                  | 14 |
| FIGURE 4: TOPSIDE BATTERY UNIT .....                           | 15 |
| FIGURE 5: RUGGED COMPUTER .....                                | 15 |
| FIGURE 6: DIVER MODEM .....                                    | 16 |
| FIGURE 7: QUICK MOUNT RELEASE .....                            | 17 |
| FIGURE 8: QUICK MOUNT WITH BEACON.....                         | 18 |
| FIGURE 9: TOPSIDE CABLE CONNECTION.....                        | 19 |
| FIGURE 10: TOPSIDE BATTERY UNIT CONNECTIONS.....               | 19 |
| FIGURE 11: COMPUTER USB CONNECTION .....                       | 19 |
| FIGURE 12: BLUETOOTH MODULE AND USB DONGLE .....               | 19 |
| FIGURE 13: DIVER6 DESKTOP .....                                | 21 |
| FIGURE 14: POOL ENVIRONMENT .....                              | 27 |
| FIGURE 15: PIER AND WHARF OPERATION .....                      | 28 |
| FIGURE 16: MARINA ENVIRONMENT – TOPSIDE MODEM POSITION 1 ..... | 29 |
| FIGURE 17: MARINA ENVIRONMENT – TOPSIDE MODEM POSITION 2 ..... | 29 |
| FIGURE 18: TOPSIDE WITH FIXED MOUNT .....                      | 30 |
| FIGURE 19: TOPSIDE HEADING TICK MARK .....                     | 30 |
| FIGURE 20: TOPSIDE MODEM FIXED CRAFT PLACEMENTS.....           | 31 |
| FIGURE 21: ADVISORY SCREEN .....                               | 37 |
| FIGURE 22: NO INTERNET CONNECTION SCREEN.....                  | 38 |
| FIGURE 23: NEWEST VERSION SCREEN.....                          | 38 |
| FIGURE 24: SOFTWARE UPDATE SCREEN .....                        | 38 |
| FIGURE 25: REGISTRATION SCREEN.....                            | 39 |
| FIGURE 26: NO DIVE MASTER SCREEN .....                         | 39 |
| FIGURE 27: DIVE MASTER LOGIN SCREEN.....                       | 40 |
| FIGURE 28: MANAGE DIVE MASTER SCREEN .....                     | 41 |
| FIGURE 29: WINDOWS PHOTO SCREEN.....                           | 42 |
| FIGURE 30: MAIN MENU .....                                     | 43 |
| FIGURE 31: MANAGE DIVER SCREEN .....                           | 44 |
| FIGURE 32: DIVER ALARM SCREEN .....                            | 45 |
| FIGURE 33: DIVER PLAN SCREEN .....                             | 46 |
| FIGURE 34: DIVER OPERATIONS SCREEN.....                        | 47 |
| FIGURE 35: DIVE RECORD .....                                   | 48 |
| FIGURE 36: COMPLETE DIVE.....                                  | 48 |
| FIGURE 37: COMMUNICATIONS SCREEN.....                          | 49 |
| FIGURE 38: MODEM ID SETUP SCREEN.....                          | 50 |
| FIGURE 39: GLOBAL ALARMS SCREEN.....                           | 51 |
| FIGURE 40: DESTINATIONS SCREEN.....                            | 52 |
| FIGURE 41: DIAGNOSTICS SCREEN .....                            | 53 |
| FIGURE 42: DIVE LOG MAINTENANCE .....                          | 54 |
| FIGURE 43: DIVE MONITORING SCREEN .....                        | 55 |
| FIGURE 44: SYSTEM QUESTION SCREEN .....                        | 55 |
| FIGURE 45: DIVER DETAILS SCREEN .....                          | 56 |
| FIGURE 46: 2D AND RANGE RING SCREEN .....                      | 58 |
| FIGURE 47: 3D SCREEN .....                                     | 58 |
| FIGURE 48: DESTINATIONS SCREEN.....                            | 58 |
| FIGURE 49: DIVER CONTROL SCREEN.....                           | 59 |
| FIGURE 50: DIVER RECALL SCREEN.....                            | 60 |
| FIGURE 51: RECALL SCREEN .....                                 | 60 |
| FIGURE 52: DIVER ASSIST SCREEN.....                            | 61 |
| FIGURE 53: DIVER PROVIDING ASSIST SCREEN .....                 | 61 |



|  |    |
|--|----|
| FIGURE 54: GO TO TARGET SCREEN .....             | 61 |
| FIGURE 55: MARK SCREEN .....                     | 62 |
| FIGURE 56: DIVER TO SEND SCREEN .....            | 63 |
| FIGURE 57: DESTINATION TO SEND DIVER SCREEN..... | 63 |
| FIGURE 58: MAPPING SCREEN .....                  | 64 |
| FIGURE 59: HISTORICAL DATA SCREEN .....          | 64 |
| FIGURE 60: BREADCRUMB DATA SCREEN.....           | 65 |
| FIGURE 61: DIVE TEAM SCREEN.....                 | 66 |
| FIGURE 62: DIVER ALARM SCREEN .....              | 67 |
| FIGURE 63: DIVE TABLE SCREEN .....               | 68 |
| FIGURE 64: SELECTED DIVE TABLES SCREEN .....     | 68 |
| FIGURE 65: NOTES SCREEN .....                    | 69 |
| FIGURE 66: DISTRESS SCREEN .....                 | 70 |
| FIGURE 67: CONFIRM DISTRESS .....                | 70 |
| FIGURE 68: RETURN HOME .....                     | 70 |
| FIGURE 69: SEND ASSIST .....                     | 70 |
| FIGURE 70: CHARTS VIEW SCREEN .....              | 76 |
| FIGURE 71: CHARTS DETAILS SCREEN .....           | 77 |
| FIGURE 72: HISTORY AND TRAILS SCREEN.....        | 77 |
| FIGURE 73: CHART LOCATION .....                  | 78 |
| FIGURE 74: CHART DIRECTORY .....                 | 79 |
| FIGURE 75: TILE SERVER PROPERTIES.....           | 79 |
| FIGURE 76: CHARTSERVER OPTION PROPERTIES .....   | 79 |
| FIGURE 77: CHART INDEX FILE.....                 | 80 |
| FIGURE 78: CCS PROGRAMMING SOFTWARE .....        | 81 |
| FIGURE 79: FIRMWARE UPGRADE PORT .....           | 81 |
| FIGURE 80: SHEARWATER® UPDATE SCREEN .....       | 82 |



# Section 1: Introduction

## Welcome

Congratulations on the purchase of your Diver6 System. Dive command and control are vastly improved with the Diver6 System, a supplemental Diver and Dive Operations Mobile Support System, which can assist Dive Masters in monitoring and tracking their divers beneath the surface of the water, thus providing greater situational awareness. The Diver6 System is designed and intended for use only by certified Dive Masters and is not intended to, nor should it, replace independent dive and contingency planning.



Diver information is transmitted via an underwater modem to a receiving unit on the surface and then to a monitoring computer that records, calculates and displays the various parameters using full 3D tracking. This means a Dive Master now has a replication of each diver's vitals, has full situational awareness of each diver, and can intervene, if required, in near real-time.

The Diver6 System uses unique Dive Master tracking and monitoring software developed by Azimuth Inc., holds a database of dive/diver information, and simultaneously provides an audit trail for diving activity. All monitoring aspects of the dive are recorded and can be used for later analysis and audit.

Dives are currently monitored for air pressure(s), depth, water temperature, and position. This means the Dive Master knows a diver's position (either absolute or relative to the dive tender), the diver's depth and descent/ascent rates, and the diver's remaining air time. Decompression tables are included in the software for reference only. No decompression calculations are currently implemented.

## Initial Checking of the Diver6 System on Arrival

On arrival the Diver6 System needs to be checked and accepted by the user for completeness and that all components function as described. These checks need to be completed in a workshop or clean environment and need to be performed before the system is used in the water. Failure to complete these checks may void the product Warranty.

The user has a period of 30 calendar days from the delivery date to complete the initial checkout of the Diver6 System. It is during this time that the user has the opportunity to identify any manufacturing faults and return faulty components for direct replacement with new components (at no cost to the user).

Please refer to the sections below for full guidance on how to set up the Diver6 System and verify the functionality of all components.



## Checking Contents

Each portable Diver6 System is typically comprised of the following items (your Diver6 System may have been customized and as such, the contents of your Diver6 System need to be checked against the packing slip in the shipping documents of your system):

### Topside Case

| Layer             | Content   |
|-------------------|---|
| Lid Storage Pouch | Topside Modem Cable (x1)<br>Power Data Cable (x1)   |
| Top               | Tablet computer with the Diver6 System software (x1)<br>Power supply for the tablet computer (x1)<br>Topside Modem (x1)<br>Topside Modem Mount (x1)<br>ICD-U80 Programmer       |
| Bottom            | Topside Battery Unit (x1)<br>Topside Battery Charger (x1)<br>Tools & Spares Kit (x1)<br>Bluetooth Connector (x1)/Dongle (x1)<br>Various AC Adapters for Topside Battery Charger |

### Diver Case

| Layer             | Content   |
|-------------------|---|
| Lid Storage Pouch |   |
| Top               | Diver Modem with Slide Mount (x4)<br>Diver Control Module (x4)<br>Diver Battery Pack (x4)                             |
| Bottom            | Diver Modem Charger (x4)<br>Diver Control Module Cables (x4)<br>Various AC Adapters for Diver Control Module Chargers |





## Disclaimer

The Diver6 System is a **SECONDARY ADVISORY SYSTEM ONLY** that is used by surface personnel to assist in the monitoring and tracking of dive operations. All dive planning and contingencies for dive operations must accommodate the likelihood of a total Diver6 System failure or environmental conditions that limit the performance of the Diver6 System. All dive supervision, planning, and contingencies must be made separate from, and without any reliance on, the features and tools of the Diver6 System.

### **The Diver6 System is not a replacement for good training and common sense.**

Dive Masters using the Diver6 System to monitor a dive must:

1. Read, understand, and agree to the disclaimer above and the disclaimer displayed when the Diver6 System was initially loaded, and
2. Certify that they have dive operational procedures in place that take account of any failure of the Diver6 System during a dive operation, and
3. Certify that they will use the Diver6 System as a **SECONDARY ADVISORY SYSTEM** only.

The developers, manufacturers, and suppliers of the Diver6 System are not liable for any claims arising from the malfunction of any individual component or the entire Diver6 System.

By using the Diver6 System the user agrees with this disclaimer and the disclaimers displayed in the Diver6 System Software. If there is any doubt about the limit of liability for the Diver6 System, the user must not use the Diver6 System.



## Warranty

The Diver6 System hardware is warranted to be free from defects for a period of:

1. 30 calendar days from the delivery date to check that all components of the Diver6 System are functioning. During this period any valid warranty claims for faulty components will be replaced with new components at no cost to the user.
2. The system warranty begins immediately from the date of customer acceptance and runs for 365 days. Customer acceptance will always be deemed to have occurred within 72 hours of delivery.

### Warranty Exclusions/Limitations

1. The Warranty does not include water damage to components other than those components that are designed to be immersed in water. The components that are designed for immersion in water are:
  - a. Topside Modem
  - b. Diver Modems
  - c. The section of the data cable from the plug that connects to the Topside Modem to within one meter (3 feet) of the Topside Battery Unit. The portable battery unit is not designed for immersion.
2. The Warranty does not include incorrect use of any component of the Diver6 System.
3. The entire Diver6 System Warranty is void if the user uses tools or equipment on any component of the Diver6 System, other than those as prescribed in this manual.
4. The Warranty does not include damage in transit.
5. The Warranty does not include the shipping costs and any applicable taxes for returning the Diver6 System or components of the Diver6 System to Azimuth for assessment and/or repair. ALL shipping costs are the responsibility of the User.
6. If any component of the Diver6 System is opened or dismantled, the entire Warranty for the Diver6 System is void.
7. The Warranty covers the full replacement of any faulty components with new components during the first 30 calendar days from the delivery date. The balance of the Warranty covers the factory repair and/or replacement of faulty components. If a valid warranty claim is made and the faulty component is beyond repair the component may be replaced with a similar refurbished item or replaced with a new item at the sole discretion of Azimuth.
8. The Warranty is not transferable. Only the original purchaser has Warranty rights. If the Diver6 System changes ownership from the original purchaser the entire Warranty becomes void.
9. All Warranty claims must be in writing.

### Procedure for Making a Warranty Claim

The procedure for making a Warranty claim is:

1. Within five working days of the discovery of a fault to any component of the Diver6 System, the user must initially contact in writing:
  - a. The local sales representative for the Diver6 System and/or



- b. Azimuth (see contact details below)

If the fault has been present for more than five working days and the user has not contacted either the local agent and/or Azimuth in writing, then Azimuth may reject the Warranty claim made by the user.

2. On initial contact (as described in 1. above) the user must detail in writing the following:
  - a. The serial number of the Diver6 System
  - b. (If applicable) The serial number of the faulty component
  - c. A description of:
    - i. The conditions in which the Diver6 System Component was being used when the fault occurred.
    - ii. A description of the fault.
3. On receiving the details of the claim as outlined in 2. above, Azimuth will respond within five working days with instructions relating to the Warranty claim (e.g. the component needs to be returned to Azimuth).
4. If a faulty component is returned to Azimuth, an initial inspection will be undertaken within five working days of receipt of the faulty component, then:
  - a. If the fault is deemed to be a genuine Warranty claim, the faulty component will be repaired or replaced with a similar refurbished component or replaced with a new component in line with the Warranty conditions.
  - b. If the fault cannot be repeated and/or simulated in the factory environment the component will be returned to the user and the user may become liable for the costs of the inspection.
  - c. If the fault, at the sole discretion of Azimuth, is due to items outlined in the Warranty Exclusions/Limitations section above, the user will become liable for the cost of the inspection and/or the repair of the faulty component and/or replacement with a similar refurbished component and/or replacement with a new component.
5. If your Diver6 System or any of your components require service or warranty repair and you are shipping from outside the United States, please contact Azimuth or your Diver6 retailer for return instructions.

**Warranty Contact Information**

For warranty questions, information, and claims:

| Contact  | Details  |
|----------|--|
| Email    | <a href="mailto:warranty@diver6.com">warranty@diver6.com</a> or your local Diver6 System Agent |
| Phone    | Your local Diver6 System Agent   |
| Shipping | Azimuth Inc.<br>136 Tower Lane<br>Morgantown, WV 26501<br>USA<br>Attn: Diver6 System Warranty  |

## Section 2: System Overview

### How does it work?

The Diver6 System uses acoustic modems to transmit data between Topside and Diver Modems. The single Topside Modem is both an acoustic modem and an Ultra Short Base Line (USBL) acoustic system that uses multiple transducers packed into a single housing to detect the range and bearing to the diver.

The acoustic component of the Diver6 System has the following signal path (Figure 1):

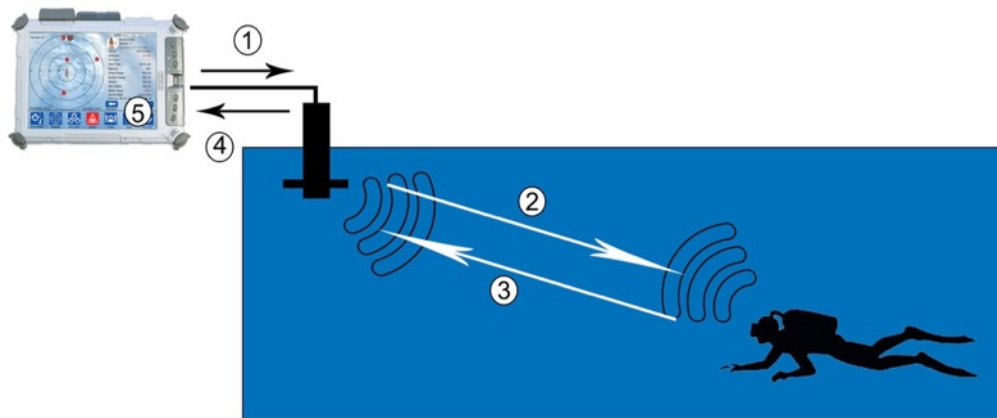


Figure 1: System Communication

1. The Diver6 System Software transmits a signal to the Topside Modem to query a Diver Modem. Each Diver Modem has an individual address (the Diver modem will show the address on boot up via the LCD on the bottom of the modem).
2. The Topside Modem transmits an acoustic signal to the Diver Modem.
3. The Diver Modem then responds with a message to the Topside Modem. These messages may contain data (e.g. diver depth, battery voltage, cylinder pressure, etc.).
4. On reception of the message from the Diver Modem, the Topside Modem can resolve the following:
  - a. The distance between the Topside Modem and the Diver Modem (this is known as the slant range and is based upon the speed of sound in water).
  - b. The compass bearing to the Diver Modem (this is based upon the angle of approach of the signal from the Diver Modem message).
5. Based upon the information received, the Diver6 System Software then:
  - a. Calculates the absolute geo-position by combining the relative position of the diver to the Topside Modem and the GPS position of the Topside Modem.
  - b. Updates the status of the diver based on the data received from the Diver Modem.



## Expected Range

The expected range of the Diver6 System will be dependent upon the conditions of deployment. Extensive range testing of the Diver6 System has demonstrated the following ranges:

1. Over 1,000 m in “ideal” conditions
2. Over 800 m in a marina environment

## Limitations on Range

### The effect of thermoclines

One of the environmental constraints of acoustic diver tracking is the interference of thermoclines. A thermocline typically happens in calm waters where a layer of warmer water is sitting on top of a layer of colder water (Figure 2).

The interface between the warmer water and the colder water can (in certain circumstances) cause significant acoustic interference and restrict the range of the Diver6 System.

If the diver is below the thermocline and the Topside Modem is above the thermocline, part of the acoustic signal between the two can be bounced off the thermocline. This effect is known as an acoustic mirror.

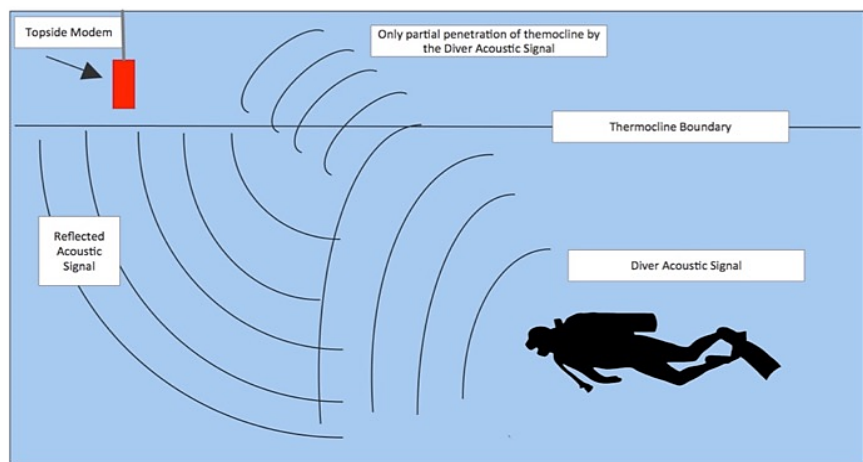


Figure 2: Thermocline Diagram

An acoustic signal that approaches the thermocline will partially travel through the thermocline with the balance of the acoustic signal being reflected. The signal is therefore dependent upon environmental conditions.

Thermoclines can significantly reduce the effective range of the Diver6 System: physical ranges in severe thermoclines have been reduced to about 60m. The best mitigation for this effect is to either lower the Topside Modem below the thermocline or reduce the range between the Topside Modem and the diver.

If both the diver and the Topside Modem are on one side of the thermocline, the acoustic signal path will be better and possibly behave much in the same way as an unobstructed signal path. If either the Diver Modem or the Topside Modem is in the thermocline, then the acoustic signal can be absorbed within the thermocline.



## Environmental effects

There may be reasons that the environmental conditions will affect the range. For example:

- If the seafloor is hard-packed sand and the water is calm without thermoclines, then the acoustic conditions will be close to ideal, and extended ranges would be expected.
- If the seafloor is loosely packed marine sediment, the seas rough, and significant ambient noise (boat traffic, oil rig noise, rain, etc.) then the lower end of ranges would be expected.
- If the seafloor is hard rock with a large number of outcrops, the range may be limited by multipathing (acoustic signal being reflected off the hard surfaces), or the Diver6 System may have a clear signal path and achieve extended ranges. It will depend upon the conditions.
- If the water is a stagnant lake with a severe thermocline, then the range may be limited to very short distances well below the expected range.



## Diver6 System Specifications

There are many components to the Diver6 System and only the main components are detailed here.

### Topside Equipment

There are three main elements to the Topside equipment.

#### Topside Modem



Figure 3: Topside Modem

The Topside Modem (Figure 3) is built around a robust broadband spread spectrum signaling scheme, this multi-purpose acoustic transponder beacon is capable of simultaneously tracking up to 14 other asset positions while undertaking bi-directional data exchange.

- Supply Voltage: 9V to 28V DC
- Operating & Storage Temp: -5°C to +35°C (23°F 95°F)
- Acoustic Range: 1km radius horizontal, 1km vertical
- Range Resolution:  $\pm 50\text{mm}$  (dependent on VOS accuracy)
- Angular Resolution:  $\pm 1^\circ$
- Communication: Broadband spread spectrum encoding, 24-32kHz, 100 baud. Multi-tiered Acoustic Protocol Stack.
- Transmit Sound Pressure Level:  $\sim 172\text{dB}$  re 1uPa @ 1m
- Size:
  - Diameter: 55mm (2.16")
  - Length: 166mm (6.3")
  - Weight: In-air - 708g (1.56lbs) / In water - 508g (1.12lbs)

### Topside Battery Unit

The topside battery (Figure 4) unit supplies the system with power to the Topside Modem and data communication to the computer.

- BB-390B/U Sealed NiMH Rechargeable Battery
  - 24V – 4.9 Amp-Hours
  - Output Protected (5A PTC Resettable Fuse)
  - ON/OFF Toggle Switch
  - Ruggedized Water-Resistant Enclosure



Figure 4: Topside Battery Unit

### Topside Monitoring Computer

The Rugged Tablet (Figure 5) is a comprehensive and fully featured rugged tablet PC with:

- Powerhouse performance: Intel® Core™ i5, 16GB RAM
- M.2 256GB SATA Class 20 SSD
- WLAN/WWAN Chassis 11.6 FHD (1920X1080) Outdoor-Readable Glove-Capable Touchscreen w/Gorilla Glass
- Extended IO Module
- Intrinsically safe for explosion-prone environments
- Designed for in-field upgrades
- Full Microsoft® Windows® 11
- Comprehensive communications suite
- Fully rugged:
  - MIL-STD-810G and IP67 tested
  - Hazardous Location Certified
  - Salt Fog Spray tested to MIL-STD-810G, M509.5
- Battery: 2-cell (26Wh) Lithium-Ion Primary Battery, Secondary Battery
- Dimensions: (WxDxH) 12.3" x 8.0" x 0.96" (312 x 203 x 24 mm)
- Weight: 1.27 kg / 2.8 lbs
- On-board u-blox NEO-M8 GPS (0.3-meter accuracy)



Figure 5: Rugged Computer

Please note that the computer manufacturer's specifications may change.





## Diver Equipment

### Diver Modem

The Diver Modem consists of the Diver Beacon and Diver Control Module (DCM) (Figure 6). The beacon communicates with the surface transmitting and receiving data. The DCM provides power to a DiveCAN connection to communicate with Shearwater® products and devices.

The specifications for the diver beacon are:

- Operating & Storage Temp: -5°C to +35°C (23°F 95°F)
- Acoustic Range: 1km radius horizontal, 1km vertical
- Range Resolution: ±50mm (dependent on velocity of sound (VOS) accuracy)
- Angular Resolution: ±1°
- Communication: Broadband spread spectrum encoding, 24-32kHz, 100 baud. Multi-tiered Acoustic Protocol Stack.
- Transmit Sound Pressure Level: ~172dB re 1uPa @ 1m
- Size:
  - Diameter: 55mm (2.16")
  - Length: 134mm (5.3")
  - Weight: In Air - 676g (1.49lbs) / In Water - 484g (1.06lbs)



Figure 6: Diver Modem

The specifications for the Diver Control Module are:

- Supply Voltage: 9V to 28V DC
- DiveCAN enabled interface for Shearwater® integration
- Removable Battery Pack with 6+ hours of charge
- Stainless Steel construction
- Sealed connections
- User upgradable firmware port
- LCD modem ID display
- Size:
  - Diameter: 69mm (2.73")
  - Height: 187mm (7.35")
  - Weight: 1kg (2.4 lbs) – NEED WATER WEIGHT



# Section 3: Getting Started

## Getting Started

This Getting Started guide is designed to initially set up the Diver6 System. For more detailed information on the operation of the Diver6 System please refer to:

- Section 4: Diver6 System Operation
- Section 5: Software
- Section 6: Maintenance
- Section 7: Trouble Shooting

Three components need to be set up for the Diver6 System to be operational:

1. Fitting the Diver6 System Equipment (Diver Modem) to the diver's SCUBA set.
2. Plugging in the Topside Modem to the Battery Unit and Monitoring Computer and placing it in the water.
3. Configuring the Monitoring Computer and monitoring a Dive Job.

## Diver

Each diver has his own Diver Modem. Optional equipment such as the Shearwater® pressure sensor and NERD or Petrel may also be available. The Diver Modem ID Number is available on the LCD screen on the DCM. After the initial power-up and boot of the Diver Modem, the ID will flash 5 times. **Note that during power up, the modem calibrates its depth sensor which in effect zeroes the depth sensor based on the current pressure reading. Therefore, it is important to turn on the modem as close to the water level as possible.**

## Attaching the Diver Beacon

The Diver Beacon can be mounted on the air cylinder by using the slide mount. The slide mount is comprised of two components. The first component is the female side of the slide mount (Mount Base), which can be mounted to an air cylinder via a strap. The second component is the male side of the slide mount (Mount Slide), which is part of the Diver Beacon.

The base is fitted under a cylinder strap on the buckle end of the cylinder strap (i.e. through only one thickness of strapping).

Please note that the Diver Beacon Mount Base should have the curved end up (Figure 7). The mount base has been designed to allow only one thickness of the cylinder strap webbing to go through the slot. This is to ensure the Diver Beacon is installed on the buckle end of the cylinder strap, so if the cylinder strap does loosen and come undone during a dive, there is less potential for the Diver Beacon to slip out of the strap.



Figure 7: Quick Mount Release



Once the base of the mount is fitted to the dive cylinder, the slide mount with the Diver Beacon can be fitted. When fitting the slide mount, ensure that the locking pin “snaps” into place to lock the slide onto the base. If the locking pin does not “snap” into place, the Diver Beacon can slide off its mount (Figure 8). To remove the Diver Beacon, pull the locking pin out, and slide the modem off the base. The locking pin can be set in the “open” position by retracting the pin and rotating the knurled knob 90 degrees.

The head of the Diver Beacon (the black molding at the top of the Diver Beacon) should be placed on the cylinder so the head is just clear of the top of the curvature of the cylinder. Both the Dive Master and the Diver must check that they are satisfied with the position of the Diver Beacon. If there is a high entanglement potential on the dive, consideration should be given to lowering the Diver Beacon to reduce entanglement potential. The Diver Beacon can be placed low on the dive cylinder but performance may be diminished by the dive cylinder creating an acoustic shadow to the Topside Modem when the diver is in certain orientations.

The Diver Modem is turned on by connecting the Diver Control Module to the Diver Beacon. The LED will show three lines indicating the modem is booting up. After that, the Modem ID will flash 5 times.

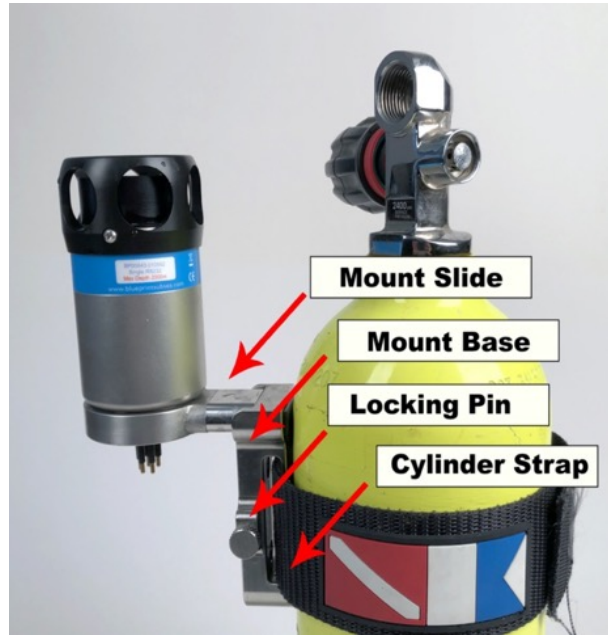


Figure 8: Quick Mount with Beacon

The DCM should be attached to the diver in a non-obtrusive location.

The red dot on the LED will also flash when it receives an Acoustic Signal from the Topside Modem.

It is relevant to note that the Diver6 System cannot be tested in the air. It is required to be submerged to work properly. For the system to operate in a non-dive scenario, the Topside Modem is required to be placed adjacent to the Diver Modem in a small pool of water. A large bucket filled with enough water to submerge the units will suffice.

### Interference with Ocean Technology Systems (OTS) Through Water Communications

The Diver6 System operates on one of the frequencies of the OTS through water communications. When the OTS communications equipment is set to Channel #1 (Buddy Phone Frequency), the Diver6 System can be heard through the OTS equipment. Selecting another channel on the OTS equipment allows both the OTS and the Diver6 System to be used at the same time.

## Topside Modem

The steps to install the Topside Modem are:

1. Connect the Topside Modem Cable to the top of the Topside Modem (Figure 9).
2. Install the battery into the Topside Battery Unit. Connect the Topside Modem Cable to the Battery Unit. Connect the Data Cable with the USB connection to the Battery Unit. Turn on the Battery Unit via the switch (Figure 10).



**THE TOPSIDE BATTERY UNIT AND BATTERY SYSTEM ARE DESIGNED FOR USE IN A RUGGED ENVIRONMENT. HOWEVER, THEY ARE NOT DESIGNED TO GET WET AND/OR IMMERSUED DUE TO BATTERY VENTING REQUIREMENTS.**

3. Connect the USB cable to the monitoring computer (Figure 11).

### Bluetooth Connection (Wireless Topside Communication)

The system can be set up to have a wireless connection between the Topside Modem and tablet computer. A Bluetooth module and dongle are provided with the system for this type of connection (Figure 12). The Bluetooth address is located on the underside of the Topside Battery Unit connect panel.

1. Connect the Bluetooth module to the Power Data connection on the Battery Unit.
2. Connect the USB dongle to the tablet computer.



**If the USB dongle has been configured and connects to the Bluetooth module, the red LED will appear solid indicating a paired connection. If the LED is flashing, this indicates the USB dongle has not established a connection to the Bluetooth module.**



Figure 9: Topside Cable Connection



Figure 10: Topside Battery Unit Connections



Figure 11: Computer USB Connection



Figure 12: Bluetooth Module and USB Dongle



## Topside Modem Mount Instructions

Assembly Instructions for Topside Modem Mount:

1. Locate the Topside mounting ring and screw set.
2. Position the mounting ring on the top of the unit.
3. Be sure the LED is visible. If it is not, the mounting unit is not placed correctly.
4. Hand screw the two mounting screws into the unit.
5. Using the provided tool, tighten the screws to fully secure the mount.





## Software

The Diver6 System Software is pre-installed on the tablet computer and can be run immediately by clicking on the icon in the taskbar (Figure 13). Also, pre-installed is Adobe® Acrobat Reader to easily view the dive logs post-deployment.

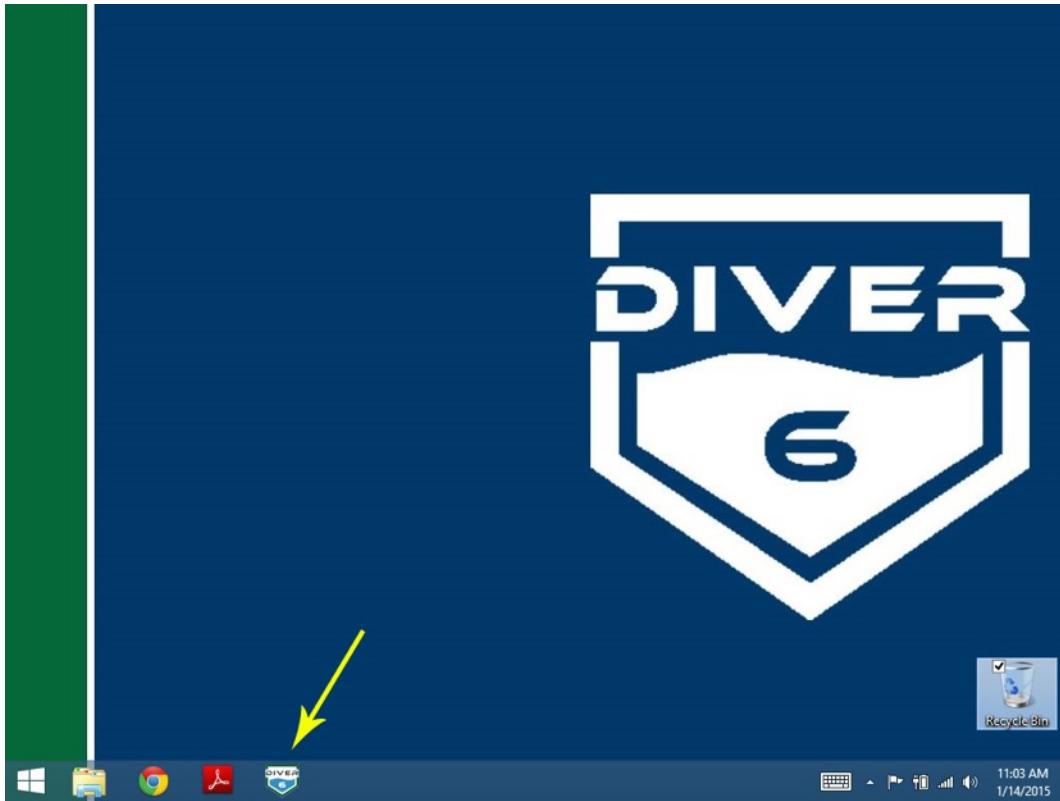


Figure 13: Diver6 Desktop

## Default Setup

| Item               | Comments   |
|--------------------|--|
| Computer Name      | Diver6tablet   |
| Default Username   | diver6   |
| Default Password   | diver6543  |
| Installed Software | The current version of Windows OS (with updates at the time of OS Build)<br>Diver6 System Software<br>Acrobat Reader<br>Tera Term<br>Chartserver |



## Getting Started Guide Summary

The Diver6 System has been designed with extensive input from subject matter experts in the diving community. The setup and deployment have been designed to have minimal impact on diving operations. The Diver6 System is a **Secondary Advisory System** only and does not replace Standard Operational Procedures, therefore the notes below are offered as a guide to getting the best out of the Diver6 System. This section is a summary only with more details given in Section 4.

### Diver

The following actions are recommended for the Diver6 System Diver deployment.

#### Pre-deployment

| Equipment   | Action Summary   |
|-------------|--|
| Diver Modem | <ol style="list-style-type: none"><li>1. Check that the Diver Modems are fully charged.<ul style="list-style-type: none"><li>• Remove the battery from the DCM.</li><li>• Plug the charger into the wall outlet.</li><li>• Once the modem is fully charged (refer to information on the charger for charging mode), unplug the charger from the wall outlet.</li></ul></li><li>2. Turn on the Diver Modem by connecting the DCM and the beacon.</li><li>3. Check operation by verifying the DCM and Beacon are on. The red dot on the LED will be visible on DCM and the Beacon will have a flashing green light.</li><li>4. Check the Diver Modem acoustic signal by running the diagnostic tests (see Section 5).</li><li>5. Attach the base of the Diver Modem Mount to the SCUBA equipment and check the functionality of the mount.</li></ol> |

#### Deployment

| Equipment   | Action Summary   |
|-------------|--|
| Diver Modem | <ol style="list-style-type: none"><li>1. Make sure the O-ring on the connector is free of defects and is lightly lubed with O-ring lube. The O-ring should have a slightly greasy appearance with no lube visible. A small tube of Christo-Lube (or similar) has been provided for this purpose. If the O-ring needs replaced use the plastic O-ring pick to remove the defective O-ring, discard it, and replace it with a new O-ring. A small tube of O-ring lube, a plastic O-ring pick, and spare O-rings are provided in the Tools &amp; Spares Kit.</li><li>2. Make sure the connector O-ring is installed in the O-ring groove. Then install the screw-on cap to protect the connector from seawater.</li><li>3. Attach the Diver Modem to SCUBA Equipment.</li><li>4. NOTE: If using a Diver6 Accessory that plugs into the connector, the rubber shoulders of the contact pins need lightly lubed with silicone grease. A tube of Dow Corning #4 Grease is provided for this purpose in the Tools &amp; Spares Kit.</li></ol> |



## Post-deployment

| Equipment   | Action Summary  |
|-------------|---|
| Diver Modem | <ol style="list-style-type: none"><li data-bbox="483 296 1448 415">1. After use, wash the Diver Modem (DCM and Beacon) with fresh water only and remove all traces of salt water and debris (do not use abrasives and/or detergent) and allow to dry.</li><li data-bbox="483 415 1448 499">2. Charge the Diver Modems and once charged, place them into the carry case for storage.</li></ol> |





## Topside Modem

The following actions are recommended for the Diver6 System Topside deployment.

### Pre-deployment

| Equipment          | Action Summary  |
|--------------------|---|
| Battery Unit/Cable | <ol style="list-style-type: none"><li>1. Check the charge of the battery.</li><li>2. Check the cable for defects (abrasions, cuts/nicks, etc.). If the cable is damaged <b>DO NOT USE!</b></li></ol>  |
| Topside Modem      | <ol style="list-style-type: none"><li>1. Check the Topside Modem for damage. If the Topside Modem is damaged <b>DO NOT USE!</b></li><li>2. Check the operation of the Topside Modem with the monitoring computer and a Diver Modem.</li></ol> |

### Deployment

| Equipment          | Action Summary   |
|--------------------|--|
| Battery Unit/Cable | <ol style="list-style-type: none"><li>1. Make sure the battery and cable are placed out of the way of Dive Operations and in an area that is as dry as possible.</li></ol>   |
| Topside Modem      | <ol style="list-style-type: none"><li>1. For more comprehensive notes on the Topside Modem deployment see Section 4.</li><li>2. With the cable and mount secure, deploy the Topside Modem in the water in such a way that the Topside Modem has a clear line of sight with the diver's operation area.</li></ol> |

### Post-deployment

| Equipment          | Action Summary  |
|--------------------|---|
| Battery Unit/Cable | <ol style="list-style-type: none"><li>1. After use, wash <b>THE CABLE ONLY (NOT THE BATTERY/BATTERY UNIT)</b> with fresh water only and remove all traces of salt water and debris (do not use abrasives and/or detergent) and allow to dry.</li><li>2. Charge the Topside Battery and once charged place it into the carry case for storage.</li></ol> |
| Topside Modem      | <ol style="list-style-type: none"><li>1. Visually check the Topside Modem for damage during transit.</li><li>2. After use wash with fresh water only and remove all traces of salt water and debris (do not use abrasives and/or detergent) and allow to dry.</li><li>3. Once dry place the Topside Modem into the carry case for transit.</li></ol>    |



## Software

The following actions are recommended for the Diver6 System Software deployment. For more comprehensive notes on using the software, see Section 5.

### Pre-deployment

| Equipment       | Action Summary   |
|-----------------|--|
| Tablet Computer | <ol style="list-style-type: none"><li>1. Ensure the tablet is charged or is connected to a power supply.</li><li>2. If an Internet connection is required, ensure that it is set up properly.</li></ol>  |
| Software        | <ol style="list-style-type: none"><li>1. If required, create a Dive Master account.</li><li>2. Verify application settings to ensure comms with Topside Modem and GPS device (if available).</li><li>3. Log in as Dive Master and configure any divers and appropriate alarm settings.</li></ol> |

### Deployment

| Equipment | Action Summary   |
|-----------|--|
| Software  | <ol style="list-style-type: none"><li>1. Configure the dive plan and start the dive.</li><li>2. Monitor dive. When a dive is completed, mark it as such by clicking the <b>Complete Dive</b> button.</li></ol> |

### Post-deployment

| Equipment       | Action Summary  |
|-----------------|---|
| Software        | <ol style="list-style-type: none"><li>1. Log out as Dive Master and quit the software.</li></ol>  |
| Topside Modem   | <ol style="list-style-type: none"><li>1. Safely disconnect the USB cable from the computer.</li></ol>   |
| Tablet Computer | <ol style="list-style-type: none"><li>1. Copy or review any dive log files.</li><li>2. Shut down the Tablet Computer.</li><li>3. Charge the Tablet Computer if necessary and once charged place it into the carry case for storage.</li></ol> |



# Section 4: Diver6 System Operation

## Introduction

This section gives detailed guidance to the deployment of the Diver6 System. The manufacturers and developers of the Diver6 System have taken care not to present this section of the manual as if it is a Standard Operating Procedure. This approach has been taken as the Diver6 System is a **Secondary Advisory System** only and does not replace existing SOPs associated with Dive Operations. It is anticipated that the notes/guidance given in this section of the user manual will be used to assist end-users in developing their own SOPs for deployment, maintenance, and support for the Diver6 System.

This section assumes that the user has read **Section 3: Getting Started**. This section provides more detailed guidance on the Installation / Deployment and Recovery of the Diver6 System hardware. For details on Software and Maintenance please refer to Sections 5 and 6.

## Topside Equipment

### Topside Modem Positioning

As outlined in Section 2 several factors influence the acoustic performance of the Diver6 System. The placement of the Topside Modem can influence the ability of the Diver6 System to monitor and track divers.

This section considers the placement of the Topside Modem in the following deployment scenarios:

1. Swimming Pool
2. Pier / Wharf
3. Marina
4. Boat

The notes provided here assume that the Topside Modem is used. The Topside Modem is provided with a hard mount. The mount is comprised of two components, the lower and upper mounts. The lower mount has threads to accept 1" NPT Stainless Steel Pipe. The upper mount has provisions for three set screws and jam nuts.

### Swimming Pool

The Diver6 System performance in a pool environment is sometimes challenging, as the acoustic signals tend to bounce off the hard walls of the pool and give rise to multi-path signals. Care is needed when setting up for use in a swimming pool:

1. Where possible place the Topside Modem away from the wall (1.0 m – 3 feet) to provide a better acoustic signal path. One way of doing this is to use the handle of a pool vacuum cleaner or similar apparatus and place it over a corner of the pool with the transducer connected mid-way across the corner (Figure 14).
2. Be aware of any acoustic shadow conditions where a diver can be hidden by an obstruction and not visible to the Topside Modem.

3. Please note that tracking will jump around a little due to multi-path signal (the acoustic signal bouncing and splitting when it encounters a hard surface). The Diver6 System can usually cope with this.
4. The Topside Modem should be placed at a depth of approximately 0.6m (2 feet) and should always (where possible) be at a lesser depth than the diver.
5. Try to set up the Diver6 System in an area where:
  - a. It is clear where the divers will be entering and exiting the water.
  - b. It is close to, but not on top of, where the Dive Master will be stationed - an area where the Dive Master can run the dive operation and also easily access the Diver6 System monitoring computer.
  - c. It is somewhere other observers can see the Diver6 System in operation, the diver in the water as well as the screen of the tablet computer.

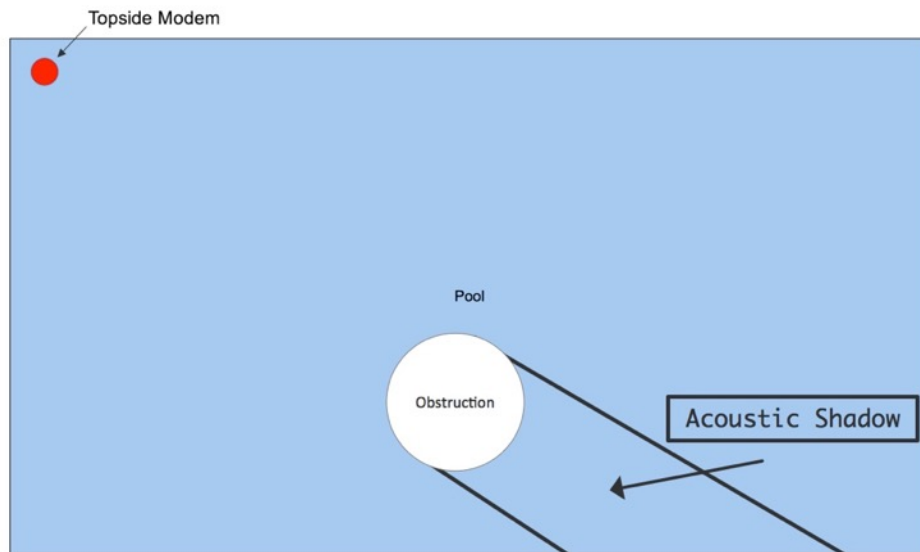


Figure 14: Pool Environment



## Pier / Wharf

Deployment of the Diver6 System from a pier/wharf is straightforward and common practice for first responders (e.g. Police, Fire, Search and Rescue).

The Topside Modem placement off a pier needs careful consideration. The Topside Modem needs to be clear of obstructions so as not to cause an acoustic shadow between the diver and the Topside Modem (Figure 15).

1. Place the Topside Modem clear of hard walls. Some piers have a concrete structure that has a vertical face well below water level and the Topside Modem needs to be placed either below the bottom of this by about 300 mm (1 foot) or 1.0 m (3 feet) clear of the wall.
2. Place the Topside Modem clear of piles. The best position is midway between piles. In most conditions, the Topside Modem can see around piles but placing it in a location where it has an unobstructed view of the diver will produce the best results.
3. Use a rigid mount to secure the Topside Modem to the pier or wharf. This will reduce the amount of swing that the transducer has and therefore increase the accuracy of the tracking.

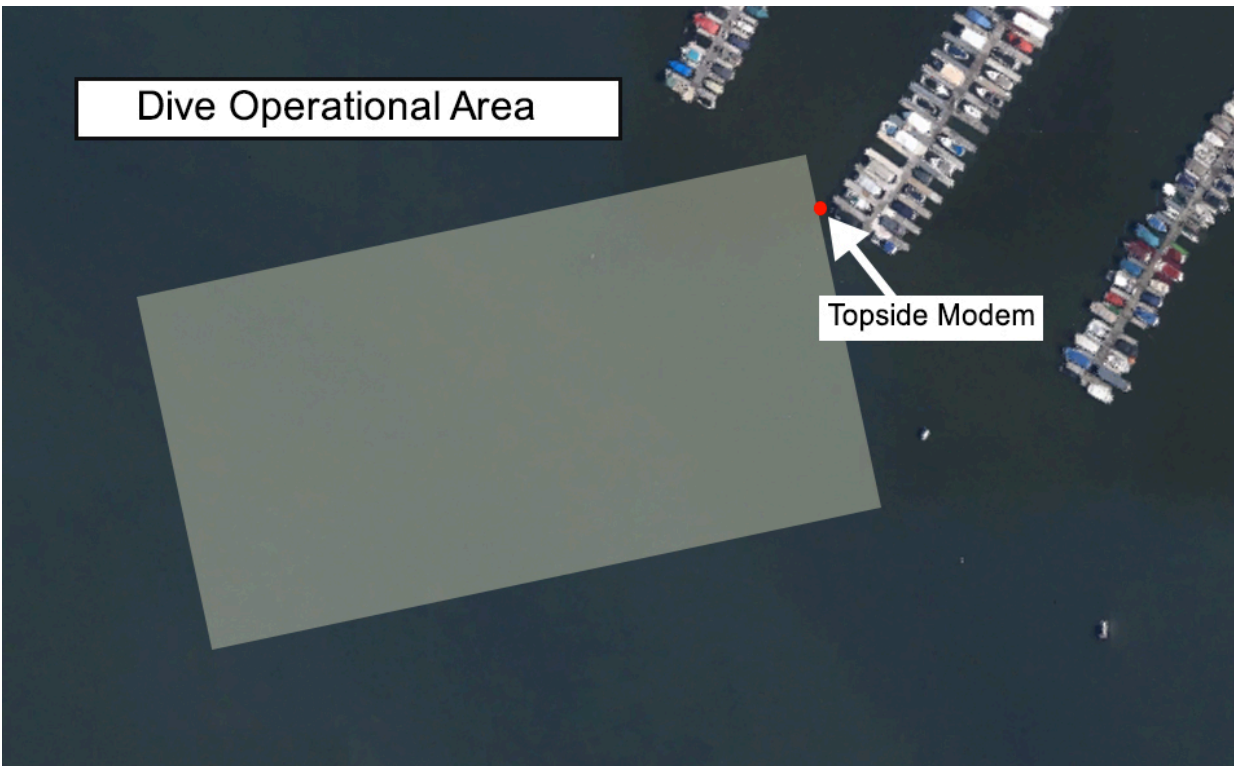


Figure 15: Pier and Wharf Operation

## Marina

Using the Diver6 System in a marina environment is very similar to that of a pier/wharf environment but has a higher likelihood of boat movements through the operational area. Therefore, all the notes associated with pier/wharf demonstrations also apply here.

Care is needed in the location selection of the Topside Modem (Figure 16, Figure 17). Also, refer to previous sections about the acoustic shadow. In a marina environment, there is a significant amount of clutter that can interfere with the Topside Modem. The best place to set up the Topside Modem is:

1. On the intersection of a marina finger when the diver is swimming up and down a marina. This way the Topside Modem can see down the length of the marina.
2. On the end of a marina finger when the diver is swimming down adjacent marinas.
3. If the dive operation is off a boat and a diver is swimming down marinas, then try to position the boat (and therefore the Topside Modem) in the center of the lane between marinas.



Figure 16: Marina Environment – Topside Modem Position 1



Figure 17: Marina Environment – Topside Modem Position 2

## Boat

Using the Diver6 System off a boat is more difficult than a stationary structure such as a pier/wharf/marina etc. as the Topside Modem tends to swing around when dangled off the boat. When using the Diver6 System from a boat, the Topside Modem Mount should be utilized (Figure 18). It is relevant to note that the more stable the Topside Modem, the more accurate the tracking component will be.

The LED on the topside modem is also the heading mark for the system. This needs to be placed at zero degrees relative to the bow of the boat. With this arrangement, limited maneuvering of the boat can be performed without the need to lift the transducer. The coxswain's view in the software is referenced to this index mark (Figure 19).

Careful consideration is needed for the Topside Modem placement. It needs to be:

1. Clear of the boat propellers. For this reason, it is not a good idea to mount the Topside Modem over the stern of the boat. If the Topside Modem is deployed over the stern of the boat, it must be lifted before the boat goes into gear.
2. Clear of the keel of the boat by about 150-300 mm (6-12 inches) and away from propeller entanglement.

An alternative to the mid-ship's deployment is off the bow of the boat using the anchor fairlead. This option is less desirable as any forward movement of the boat will result in the Topside Modem hitting the hull of the boat. A fixed mount is highly recommended to prevent the Topside Modem from spinning in the water and causing inaccuracies (Figure 20).



Figure 18: Topside with Fixed Mount



LED is Heading Tick Mark

Figure 19: Topside Heading Tick Mark



Figure 20: Topside Modem Fixed Craft Placements





## Topside Equipment Deployment Actions

The following are the recommended actions to check the operation of the Topside Equipment pre-, during, and post-deployment. Although some of the deployment actions are noted in **Section 3: Getting Started**, they are repeated in this section for completeness.

### Topside Equipment Pre-Deployment Actions

| Equipment               | Action Summary  |
|-------------------------|---|
| Battery Unit/Cable      | <ol style="list-style-type: none"><li>1. Check the charge of the battery.</li><li>2. Check the cable for defects (abrasions, cuts/nicks, etc.). If the cable is damaged <b>DO NOT USE!</b></li><li>3. Check the plug end of the cable for damage (i.e. no bent or broken pins). If the plug is damaged <b>DO NOT USE!</b></li></ol>   |
| Monitoring Computer     | <ol style="list-style-type: none"><li>1. Check the charge on the battery.</li><li>2. Check computer operation by turning it on and running the Diver6 System Software.</li><li>3. Check the Diver database and equipment configuration. Where possible configure the computer for the planned tasks at hand.</li></ol>  |
| Topside Modem           | <ol style="list-style-type: none"><li>1. Check the Topside Modem for damage. If the Topside Modem is damaged <b>DO NOT USE!</b></li><li>2. Check the operation of the Topside Modem with the monitoring computer and a Diver Modem.</li></ol>   |
| Pre-Pack for Deployment | <ol style="list-style-type: none"><li>1. Once all the Diver6 System Equipment has been checked and found to be fully operational, pack the Topside equipment into its carry case ready for deployment. Check the following are packed:<ul style="list-style-type: none"><li>• Topside Battery</li><li>• Topside Battery Unit</li><li>• Topside Modem Cable</li><li>• Power Data Cable</li><li>• Topside Modem</li><li>• Monitoring Computer</li></ul></li></ol> |



### Topside Equipment Deployment Actions

| Equipment                | Action Summary  |
|--------------------------|---|
| Battery Unit/Cable       | <ol style="list-style-type: none"><li>1. Make sure the battery and cable are placed out of the way of Dive Operations and in an area that is as dry as possible.</li></ol>  |
| Topside Modem Deployment | <ol style="list-style-type: none"><li>1. Attach the cable to the Topside Modem. NOTE: The shoulders of the male pins on the cable plug should appear greasy. Please lightly grease the rubber shoulders of the pins with silicone grease. A tube of Dow Corning #4 is provided in the Tools &amp; Spares Kit for this purpose. Please lube the shoulders with the cable detached from the Topside Battery Unit.</li><li>2. Based upon the Dive Operations area select a location to deploy the Topside Modem (see notes above for guidance on placement).</li><li>3. With the cable and mount secure, deploy the Topside Modem in the water in such a way that the Topside Modem has a clear line of sight with the diver's operation area. It is recommended that a safety line (rope, stainless steel cable) be connected to the Topside Modem in the event the modem gets disconnected from its fixed mount.</li></ol> |

### Topside Equipment Post Deployment Actions

| Equipment           | Action Summary  |
|---------------------|---|
| Battery Unit/Cable  | <ol style="list-style-type: none"><li>1. After use wash <b>THE CABLE ONLY (NOT THE BATTERY/BATTERY UNIT)</b> with fresh water only and remove all traces of salt water and debris (do not use abrasives and/or detergent) and allow to dry.</li><li>2. Visually check the battery unit/cable for damage.</li><li>3. Charge the Topside Battery and once charged place it into the carry case for storage.</li></ol> |
| Monitoring Computer | <ol style="list-style-type: none"><li>1. Charge the monitoring computer battery.</li><li>2. Check computer operation by turning it on and running the Diver6 System Software.</li><li>3. Optionally, copy the Dive Record Sheets onto an external storage device.</li></ol>   |
| Topside Modem       | <ol style="list-style-type: none"><li>1. Visually check the Topside Modem for damage.</li><li>2. After use wash with fresh water only and remove all traces of salt water and debris (do not use abrasives and/or detergent) and allow to dry.</li><li>3. Once dry place the Topside Modem into the carry case for transit.</li></ol>   |



## Diver Equipment

The following actions are recommended for the Diver6 System Diver deployment. As with the Topside Equipment, some of the deployment actions are repeated from **Section 3: Getting Started** of this manual.

### Diver Equipment Pre-Deployment Actions

| Equipment   | Action Summary  |
|-------------|---|
| Diver Modem | <ol style="list-style-type: none"><li>1. Check that the Diver Modems are fully charged.</li><li>2. Check operation by verifying the Diver Modem is on. A red dot on the LED will be visible.</li><li>3. Check the Diver Modem acoustic signal by running the diagnostic tests (see Section 5).</li><li>4. Attach the base of the Diver Modem Mount to the SCUBA equipment and check the functionality of the mount.</li></ol> |

### Diver Equipment Deployment Actions

| Equipment   | Action Summary  |
|-------------|---|
| Diver Modem | <ol style="list-style-type: none"><li>1. Make sure the O-ring on the connector is free of defects and is lightly lubed with O-ring lube. The O-ring should have a slightly greasy appearance with no lube visible. A small tube of Christo-Lube (or similar) has been provided for this purpose. If the O-ring needs replaced use the plastic O-ring pick to remove the defective O-ring, discard it, and replace it with a new O-ring. A small tube of O-ring lube, a plastic O-ring pick, and spare O-rings are provided in the Tools &amp; Spares Kit.</li><li>2. Make sure the connector O-ring is installed in the O-ring groove. Then install the screw-on cap to protect the connector from seawater.</li><li>3. Attach the Diver Modem to SCUBA Equipment.</li><li>4. NOTE: If using a Diver6 Accessory that plugs into the connector, the rubber shoulders of the contact pins need lightly lubed with silicone grease. A tube of Dow Corning #4 Grease is provided for this purpose in the Tools &amp; Spares Kit.</li><li>5. As with all sealed SCUBA equipment, when not in use keep the Diver Modem dry to prevent the Diver Modem from overheating in direct sunlight. If the Diver Modem heats up too much the internal pressures may build to the point where internal O-rings are compromised. This could result in water damage to the Diver Modem.</li></ol> |



## Diver Equipment Post-Deployment Actions

| Equipment   | Action Summary  |
|-------------|---|
| Diver Modem | <ol style="list-style-type: none"><li data-bbox="480 317 1435 422">1. After use, wash the Diver Modem with fresh water only and remove all traces of salt water and debris (do not use abrasives and/or detergent) and allow drying.</li><li data-bbox="480 432 1435 640">2. Charge the Diver Modems and once charged, place them into the carry case for storage. NOTE: Before plugging the charger into a power source, please verify that the rubber shoulders of the male contact pins on the plug are lightly lubed with silicone grease. The shoulders should have a greasy appearance. A tube of Dow Corning #4 Grease is provided for this purpose in the Tools &amp; Spares Kit.</li></ol> |



# Section 5: Software

## Software Summary

The Diver6 System software is a supplemental Diver and Dive Operations Mobile Support System, which can assist Dive Masters in monitoring and tracking their divers beneath the surface of the water providing greater situational awareness. The Diver6 System is designed and intended for use only by certified Dive Masters and is not intended to, nor should it, replace independent dive and contingency planning.

The Diver6 System software gives the Dive Master the ability to create a dive plan that assists in the monitoring and tracking of diving operations. All monitoring aspects of the dive are recorded and can be used for later analysis and audit. The Diver6 software provides up-to-date information on the divers in the water allowing the Dive Master to make faster, safer, and more accurate decisions.

The Diver6 software creates a folder called “diver6” in the User’s documents directory. This folder will contain the database and all dive logs organized by date/time-stamped folders.

## System Requirements

The Diver6 System software will run on both 64-bit Windows and Macintosh OS X platforms.

| Windows          | Mac OS X   |
|------------------|--|
| Windows 8.1 - 11 | Mac OS X 10.14 or later (Chart Server not provided). |

## Optional Hardware

The Diver6 System software can interface to optional hardware devices including the Petrel, the Near Eye Remote Display (NERD), and tank pressure sensors by Shearwater® Research Inc. (<http://www.shearwaterresearch.com>). In certain circumstances, the Diver6 System will have increased functionality and additional software features as they become available. These changes will be documented in the appropriate sections below.



## Using the Software

Upon each execution of the Diver6 System software, an advisory screen is presented (Figure 21). Read and click the Agree button to accept the conditions presented and continue using the software. Clicking the Disagree button will terminate the execution of the software. If the computer has an Internet connection, clicking on the Diver6 or Azimuth logo will open a web browser to the appropriate website. The Diver6 System software supports different languages and will display a popup list of currently supported languages at the bottom of the screen. To obtain the most recent language database and support files, use the “Check for Updates” button.

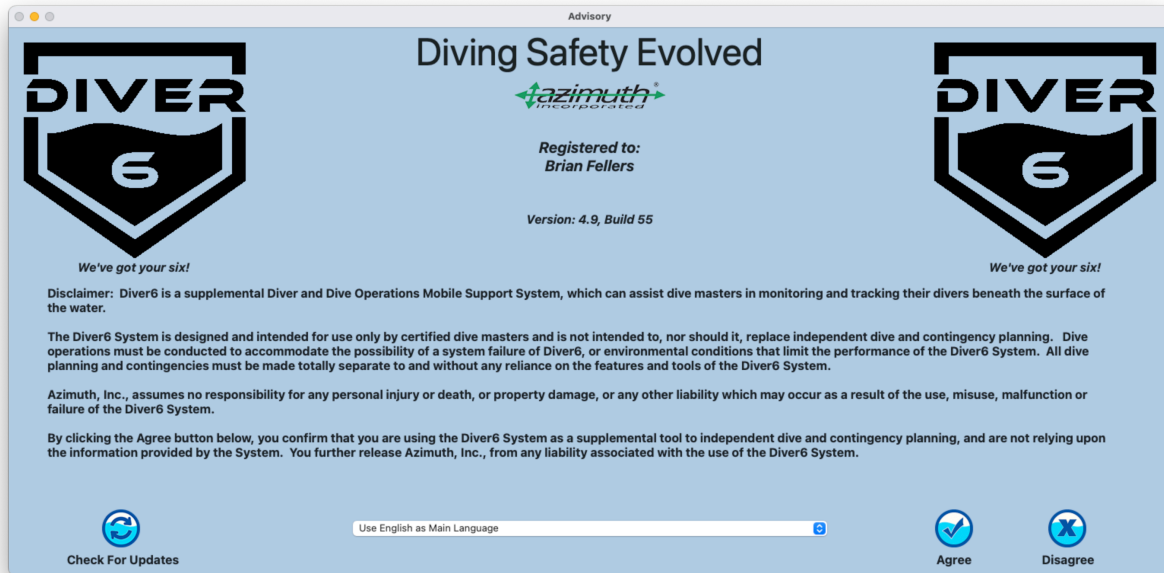


Figure 21: Advisory Screen

## Software Update

When the Advisory Screen is presented, the user can manually check for a newer version of the software, obtain the most recent language database file, and download any updated charting support files. When the “Check for Updates” button is pressed, the software will attempt to connect to the update server and check for a newer version as well as download the most recent language database and supporting files. If the computer does not have an Internet connection, a message indicating so will be displayed (Figure 22).

If an Internet connection exists, the language database file and other supporting files will automatically be downloaded. Then, a message box will be displayed indicating the status (either being up to date (Figure 23) or that a newer version is available). If a newer version is found, a window displaying the information about the update will appear. The user may click the link to download the newest installer from the Diver6 website or skip it for now (Figure 24). This check may be done anytime from the Advisory screen.

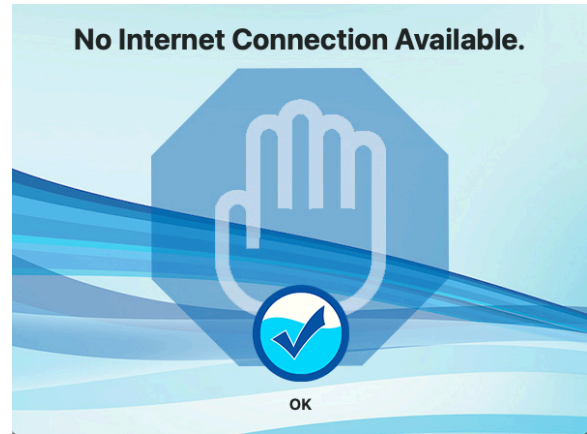


Figure 22: No Internet Connection Screen

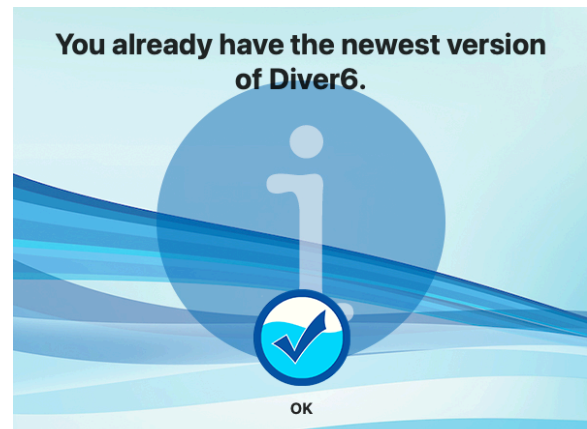


Figure 23: Newest Version Screen



Figure 24: Software Update Screen



## Registration

Upon delivery of your system, the software is automatically registered with a name and registration number. The registration information is included as part of your Diver6 System if the software is installed on a different computer or the Diver6 database is erased (Figure 25).

When new **major** software versions are released, a new registration number will be required. Please contact us for a new registration number.

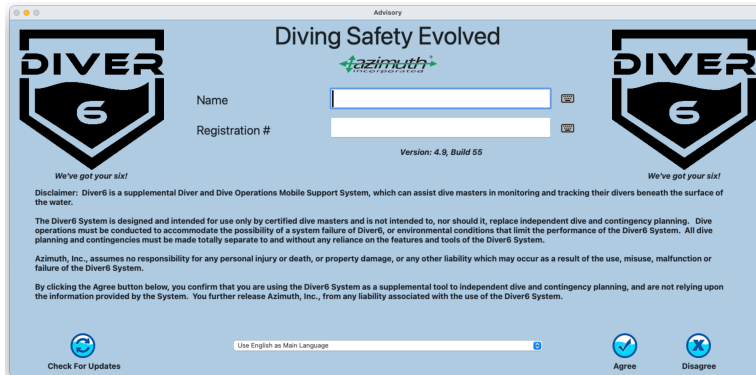


Figure 25: Registration Screen

## Dive Master Login Screen

After agreeing to the advisory screen and entering any required registration information, the main Dive Master login screen is presented. Initially, a message indicating that no Dive Masters have been created yet will be displayed as shown (Figure 26).

From this screen, the user can log in as a Dive Master and proceed to the main menu or manage (create, edit, and delete) Dive Masters by clicking on the **Manage Dive Masters** button. To end the program, click the **Quit** button.

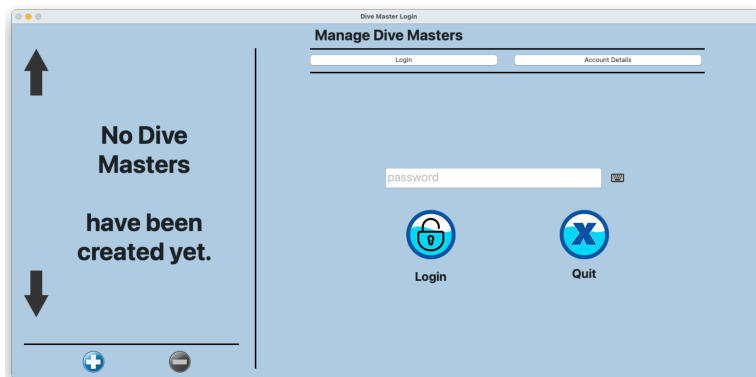


Figure 26: No Dive Master Screen





## Logging In

After clicking on a Dive Master's picture (Figure 27) the Dive Master's name will appear above the password field. Enter the Dive Master's password in the field using either a physical keyboard or a virtual one (provided by the operating system). The virtual keyboard can be manually activated by clicking on the small keyboard icon to the right of the password field. Once the password is entered, either press the **Return** key on a physical keyboard or click the **Login** button. If the password is correct, the user will then be taken to the Main Menu.

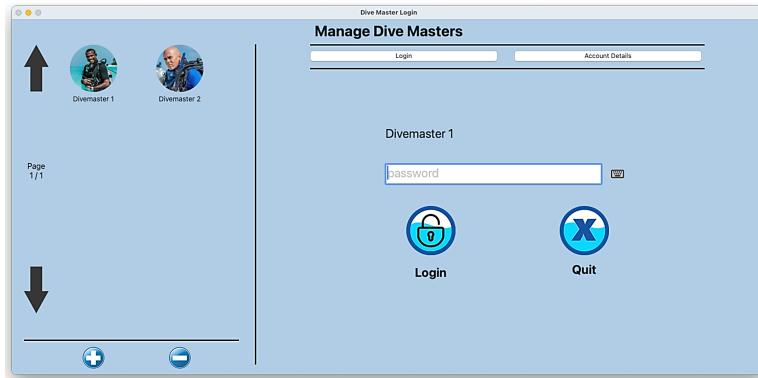


Figure 27: Dive Master Login Screen

The Dive Master Login Screen can display up to six (6) Dive Masters at once. If your system has more Dive Masters, the up and down arrow buttons allow the user to switch pages and a page indicator appears near the top of the screen.

The Account Details tab allows the user to create and modify existing Dive Master profiles.

## Manage Dive Masters

The Account Details screen (Figure 28) allows a Dive Master to create, edit, and delete Dive Master accounts. Existing Dive Masters (up to six at a time) will be shown on the left side of the screen. Page up and page down buttons will become active when more than six Dive Masters are available.

When clicking on any Dive Master icon, the associated data will be displayed on the right side of the screen. The **Edit Dive Master** and **Delete Dive Master** buttons will also activate. The Dive Master data will be read-only until the **Edit Dive Master** button is pressed.

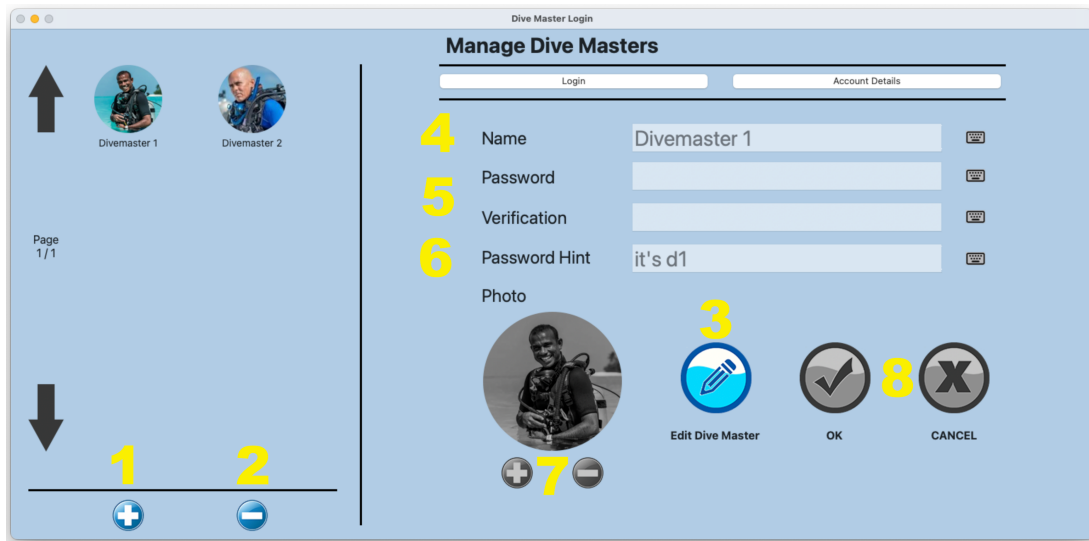


Figure 28: Manage Dive Master Screen

1. **Create Dive Master** – Allows the user to create a new Dive Master. The user will then be able to insert a new username, password, password hint, and photo.
2. **Delete Dive Master** – Allows the user to delete an existing Dive Master. A confirmation box will be presented to confirm this action. **Note:** No password is required for this operation.
3. **Edit Diver Master** – Allows the user to edit an existing Dive Master. The password for that Dive Master account will be requested before any editing is allowed.
4. **User Name** – The name given to a Dive Master.
5. **Password / Verification** – A two-step verification for the Dive Master account password.
6. **Password Hint** – Dive Masters can enter a hint to remember their password. The hint will be shown on the Dive Master login screen after three failed attempts.
7. **Choose / Clear Photo** – The Choose Photo button accesses any onboard/attached camera to take or choose photos (See **Choose Photo** for Details). The Clear Photo button clears the current image. The photo area also provides drag and drop support allowing JPEG and PNG files to be dropped on this location.
8. **OK / Cancel** – The **OK** button will save the changes and the **CANCEL** button will revert to the original data.

## Choose Photo

Any onboard/attached camera can be used to take an image of the Dive Master, diver, or destination.

The camera viewfinder in the upper left allows the user to focus on the subject and capture the image. This image will appear in the Photo Profile in the lower right. Each time an image is taken, the Photo Profile will update with the latest image.

The Choose Photo Screen provides the following operations (Figure 29):

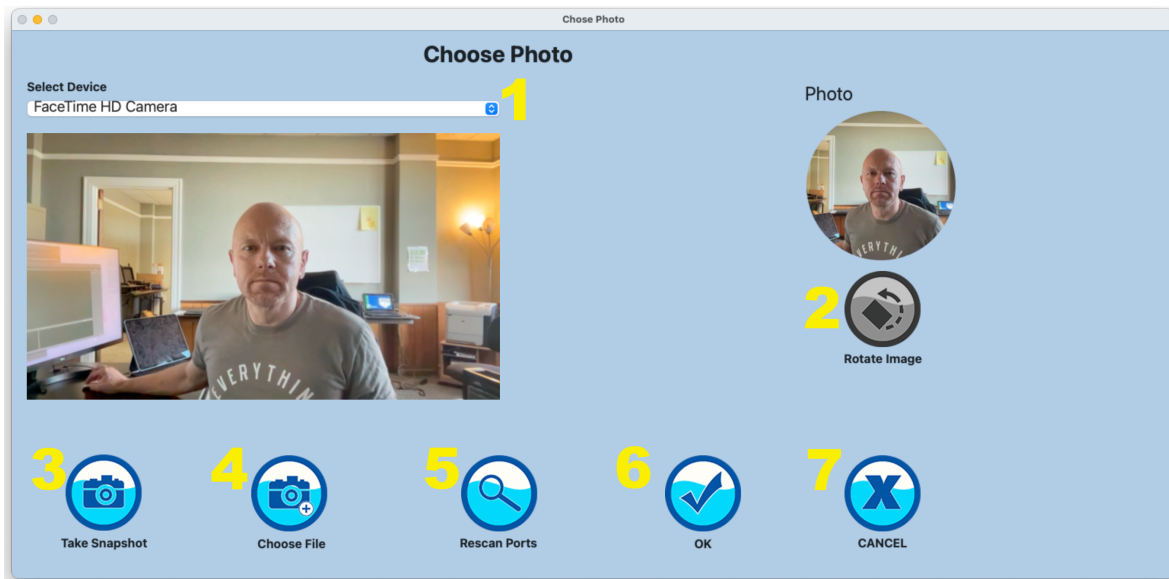


Figure 29: Windows Photo Screen

1. **Select Device** – onboard/attached camera devices appear in this box.
2. **Rotate Image** – rotates the image 90, 180, 270 degrees (Windows only).
3. **Take Snapshot** – this button captures the image and places it in the Photo Profile in the lower right.
4. **Choose File** – To use an existing image, choose this button, and a file dialog box will appear.
5. **Rescan Ports** – This button will rescan the ports looking for additional cameras that may have been connected.
6. **OK** - Returns to the previous screen and save the image in the Photo Profile in the respective profile.
7. **Cancel** - Leaves the Choose Photos screen and makes no changes.



## Main Menu

When a Dive Master successfully logs in, the Main Menu screen (Figure 30) will appear. The Dive Master picture and name appear in the lower left area of the screen. Each of the main buttons is explained below. Note that some of these buttons will deactivate when a dive is being performed.

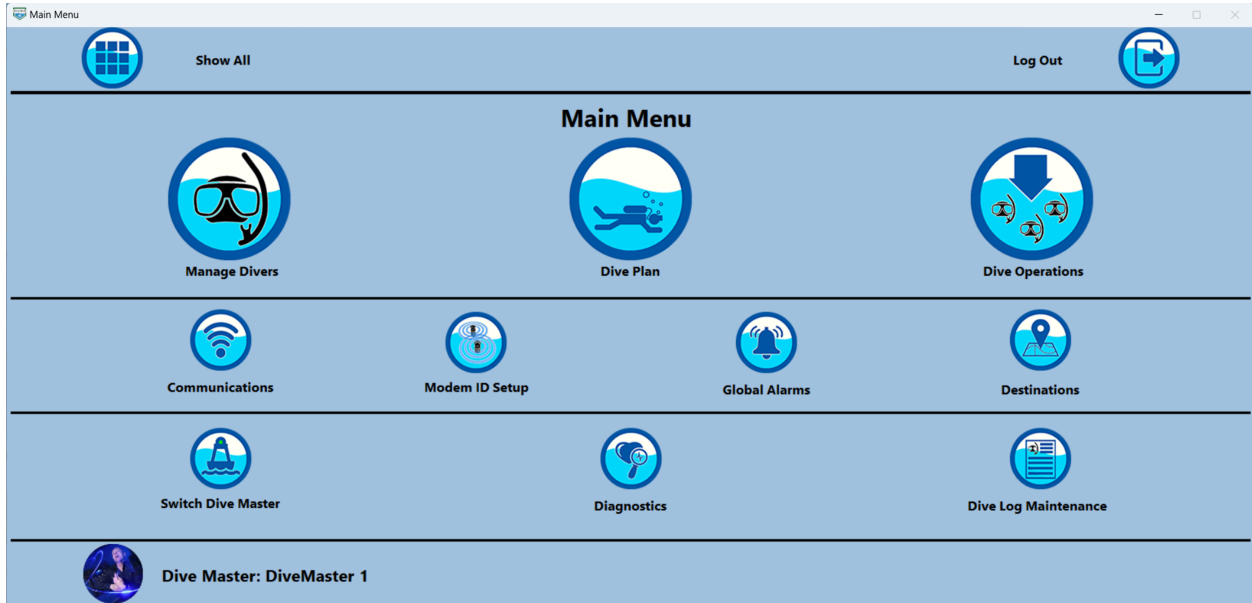


Figure 30: Main Menu



## Manage Divers

Clicking the **Manage Divers** button will allow the Dive Master to create, edit, and delete divers as well as edit alarm conditions associated with a diver. Existing divers (up to six at a time) will be shown on the left side of the screen. Page up and page down buttons will become active with more than six dive divers are available (Figure 31).

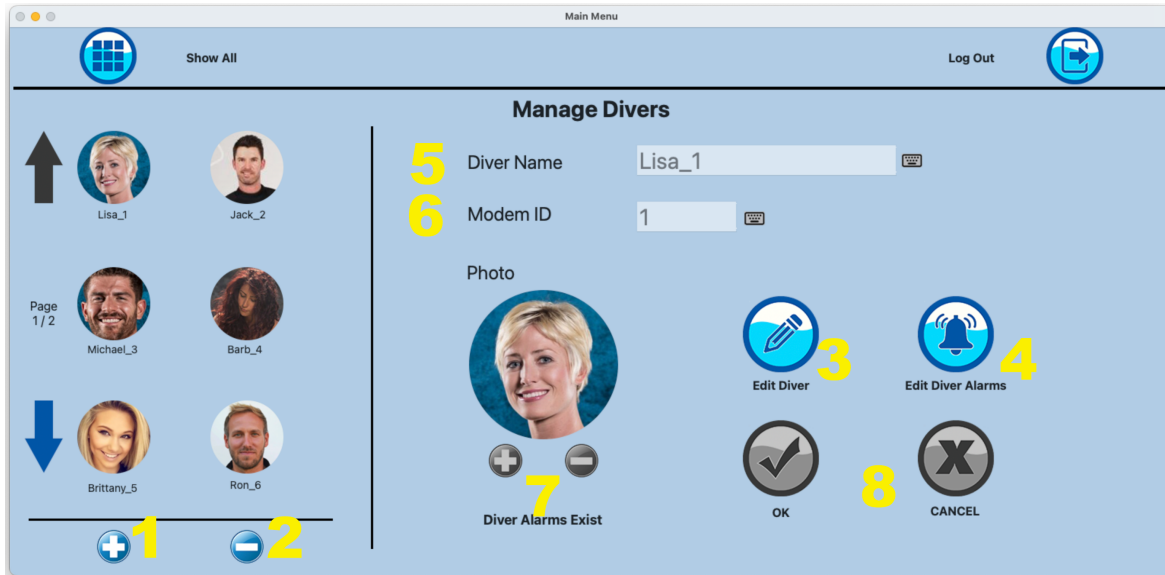


Figure 31: Manage Diver Screen

1. **Create Diver** – Allows the user to create a new diver. The user will then be able to insert a new username, password, password hint, and photo.
2. **Delete Diver** – Allows the user to delete an existing diver. A confirmation box will be presented to confirm this action. **Note:** No password is required for this operation.
3. **Edit Diver** – Allows the user to edit an existing diver. The password for that diver account will be requested before any editing is allowed.
4. **Edit Diver Alarms** – The Dive Master can edit specific alarms for the selected diver.
5. **Diver Name** – The name given to a diver.
6. **Modem ID** – The ID of the diver modem (Displayed on the LED on the bottom of the modem).
7. **Choose / Clear Photo** – The Choose Photo button accesses any onboard/attached camera to take or choose photos (See **Choose Photo** for Details). The Clear Photo button clears the current image. The photo area also provides drag and drop support allowing JPEG and PNG files to be dropped on this location.
8. **OK / Cancel** – The **OK** button will save the changes and the **CANCEL** button will revert to the original data.



When clicking on any diver icon, the associated data will be displayed on the right side of the screen. The **Edit Diver**, **Edit Diver Alarms**, and **Delete Diver** buttons will also activate. The diver data will be READ ONLY until the **Edit Diver** button is pressed. When the **Edit Diver** button is pressed, all fields can be edited, including the associated picture.

When the **Edit Diver Alarms** button is pressed, the Diver Alarms screen is displayed (Figure 32). For quick reference, the global alarm settings are displayed below the edit fields in the Diver Alarms screen. The **OK** button will save the changes and the **Cancel** button will discard any changes. Check any boxes for alarms you wish to set and then fill in the alarm value. The units displayed can be toggled between U.S. (Pounds per Square Inch (PSI), Feet, Fahrenheit) and Metric (Bar, Meters, Celsius) by clicking the **Toggle Units** button.

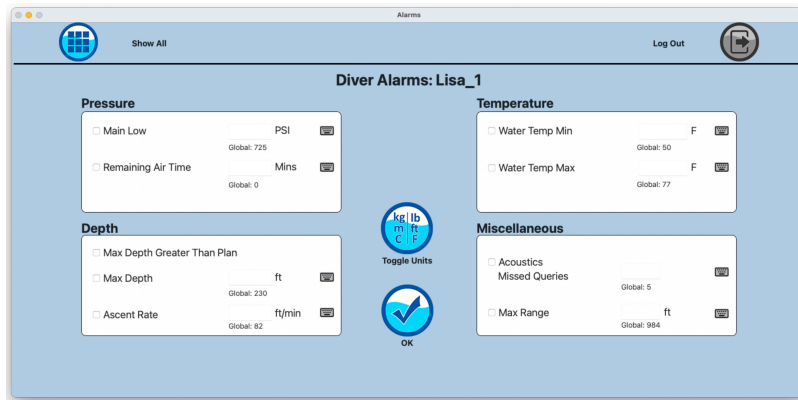


Figure 32: Diver Alarm Screen

Diver alarms must be more restrictive than global alarms (discussed in the Global Alarms section). While a global alarm applies to all divers, a diver alarm will apply to the selected diver only and can be set with more restrictions. If invalid values are entered (i.e. less restrictive than global alarms), these fields will be highlighted in red when pressing the **OK** button and need to be fixed before the data will be saved. Diver alarms can be useful when a diver is not in optimal condition (recently dived, fatigued, dehydrated, etc.) and the Dive Master wants to watch this diver a little more closely.

For example, the default global alarm for Main Low Pressure is 50 bar (725 PSI). If this is satisfactory for the chosen diver, then nothing needs to be done. However, if you want to apply a little more restriction so the alarm is triggered sooner, you could set that diver alarm at 65 bar (943 PSI). This indicates that if that diver's tank pressure value drops to 943 PSI, the diver alarm will trigger. It is not until the diver's tank pressure value drops even further to 725 PSI that the global alarm will trigger, thus making the diver alarm a more restrictive early warning feature.



## Dive Plan

The Dive Plan screen (Figure 33) allows a Dive Master to configure the dive details and dynamically manage personnel in the operation. Note: Please make sure that your Topside and GPS comms are configured before you start.

The screenshot shows a web application window titled "Dive Plan". The window has a light blue header with "Main Menu" in the center, "Show All" on the left, and "Log Out" on the right. Below the header is a "Dive Plan" section with a white background. It contains five numbered fields: 1. "Dive Name" (text input), 2. "Description" (text input), 3. "Location" (text input), 4. "Max Depth (required)" (text input), and 5. "Units" (radio buttons for "Feet" and "Meters"). A red note is displayed: "Note: Please make sure Topside and/or GPS comms have been configured." At the bottom of the form is a "Dive Operations" button with a downward arrow icon.

Figure 33: Diver Plan Screen

### Data Descriptions

1. **Dive Name (Optional)** – the name given to the dive
2. **Description (Optional)** – a description of the dive
3. **Location (Optional)** – the location of the dive
4. **Max Depth (Required)** – the maximum planned depth for this dive
5. **Units (Required)** – metric or standard

Once the dive plan information is entered, click the **Dive Operations** button to place your divers in the water.



## Dive Operations

The Dive Operations screen allows the Dive Master to place divers in and out of the water. The user can monitor and complete the active dive from this location.

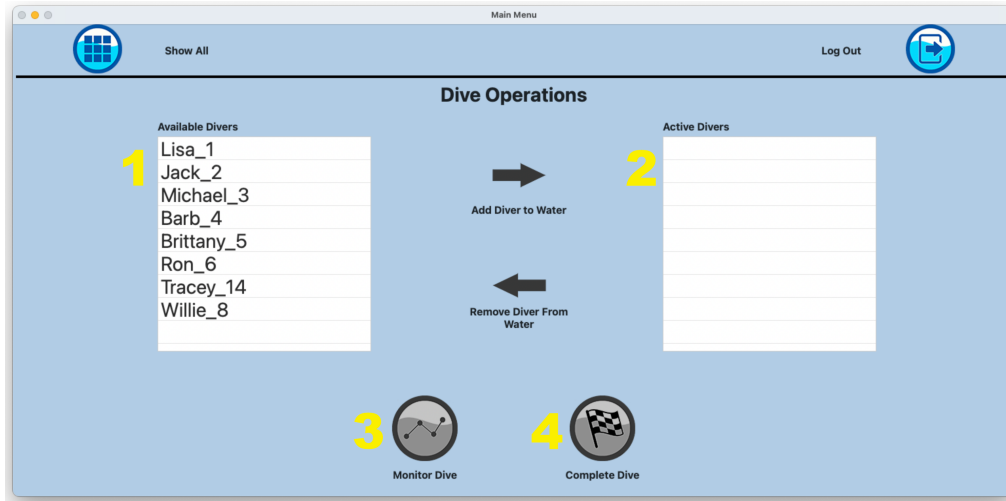


Figure 34: Diver Operations Screen

### Data Descriptions

1. **Available Divers** – the list of divers that can be used. Each time a diver is put in the water, the **Available Divers** list is filtered to remove any divers that would cause conflicts (e.g. divers with the same Modem ID).
2. **Active Divers** – divers currently in the water
3. **Monitor Dive** – displays monitoring screens to track and control all diving operations. See the Dive Monitoring section.
4. **Complete Dive** – completes the dive and generates the reports

Double-click a diver in the **Available Divers** column or select that diver and press the right arrow to add the diver to the water. As soon as the first diver is added, monitoring of the diver begins.

When the first diver is put in the water, the dive plan information fields remain but the Max Depth, and Feet/Meters Radio Buttons become disabled. This will allow a Dive Master to update the dive plan text details at any time before the completion of the dive (Figure 34). The diver put in the water is removed from the **Available Divers** list and moved to the **Active Divers** list. Each time a diver is put in the water, the **Available Divers** list is filtered to remove any divers that would cause conflicts (e.g. divers with the same Modem ID).





During the dive, divers can be added or removed from the dive as required. When a diver is removed from the water (the diver must be on the surface), a dive report is created as well as a record in the history database.

The **Complete Dive** button will first check that all active divers are on the surface. If so, the divers will be removed and dive reports (Figure 35) and database records will be created. A final dive report is created with all diver reports combined as well as any notes documented during the dive (See the Notes section). Also, a Comma Separated Value (CSV) file is created with date/time-stamped data for each diver as updated information was received during the dive.

If all active divers are not marked as being on the surface, an alert dialog box will be presented stating so. This situation can occur if a diver surfaces quickly and his modem comes out of the water preventing any final acoustic communications from notifying the software that the diver is actually on the surface. The Dive Master may therefore enter his password as a confirmation that all divers are on the surface and the dive is complete. (Figure 36) This feature is added as a convenience. The other method to accomplish this is to return to the monitoring screens and manually mark each diver as on the surface.

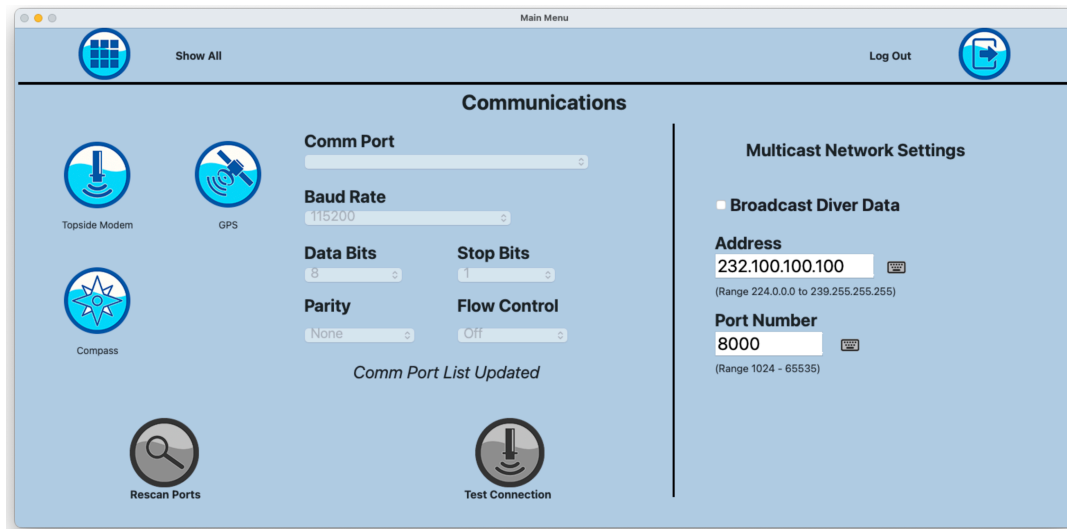
Figure 35: Dive Record



Figure 36: Complete Dive

## Communications

The Communications screen allows the Dive Master to set up the communications port settings to the Topside Modem, a Global Positioning System (GPS) device an external compass. (Figure 37). The external compass can be very useful in a situation where the built-in compass might be influenced by the local environment. Magnetic mineral deposits, large iron or steel bodies, electrical engines, or strong permanent magnets are just a few sources that can introduce errors to magnetic compass readings. The external compass port will override the built-in compass. If the external compass port is disconnected or data is not received within ten seconds (a timeout occurs), the software will default back to the built-in compass.



**Figure 37: Communications Screen**

To configure a device, first select the appropriate device on the left side of the screen. Then, choose the settings (Comm Port) for that device. If your device does not show up in the **Comm Port** popup list, first ensure the device is plugged in, turned on, and any drivers are installed. Click the **Rescan Ports** button and check the **Comm Port** popup list again to choose the correct device.

During the GPS test, the software will listen for the GGA or GLL National Marine Electronics Association (NMEA) 0183 sentence. If either string is received, a success message will be displayed. Otherwise, the failure message will appear.

During the Compass test, the software will listen for the HDG or HDM NMEA 0183 sentence. If either string is received, a success message will be displayed. Otherwise, the failure message will appear.

To verify the Topside Modem, GPS, or Compass settings, click the **Test Connection** button. The status text will appear above this button indicating success or failure.

To establish the Bluetooth connection (for wireless Topside Modem communication), be sure to connect the Bluetooth module to the Topside Battery Unit and the USB dongle to the tablet computer.

The Multicast Network Settings section allows the Dive Master to choose a Broadcast Address and Port Number for a User Datagram Protocol (UDP) interface to allow diver data to be transmitted on the network. This allows other systems to easily import the information for data collection and processing. One such system is HYPACK® ([www.hypack.com](http://www.hypack.com)).



The format of the datagram is a comma-delimited string of values for each diver with the following fields:

- Diver6 Prefix/Beginning of string (\$DIVER6)
- Diver # (up to 3 digits)
- Diver Name
- Range (meters)
- Azimuth (degrees)
- Depth (meters)
- Water Temperature (Celsius)
- Maximum Depth (deepest diver has gone)
- Tank Pressure 1 (BAR) (or an empty string if no data exists)
- Tank Pressure 2 (BAR) (or an empty string if no data exists)

### Modem ID Setup

The Modem ID setup screen allows the Dive Master to change the ID of one modem at a time.

Unplug the Topside Modem from the five-pin cable. Using this cable, connect the Diver Beacon (Diver Modem) directly.

Click the **Query Diver ID** button (Figure 38) and when a modem is found, the ID will be displayed in the text area on the right side of the screen.

Once found, enter the new modem number in the field and press the **Change Diver ID** button.

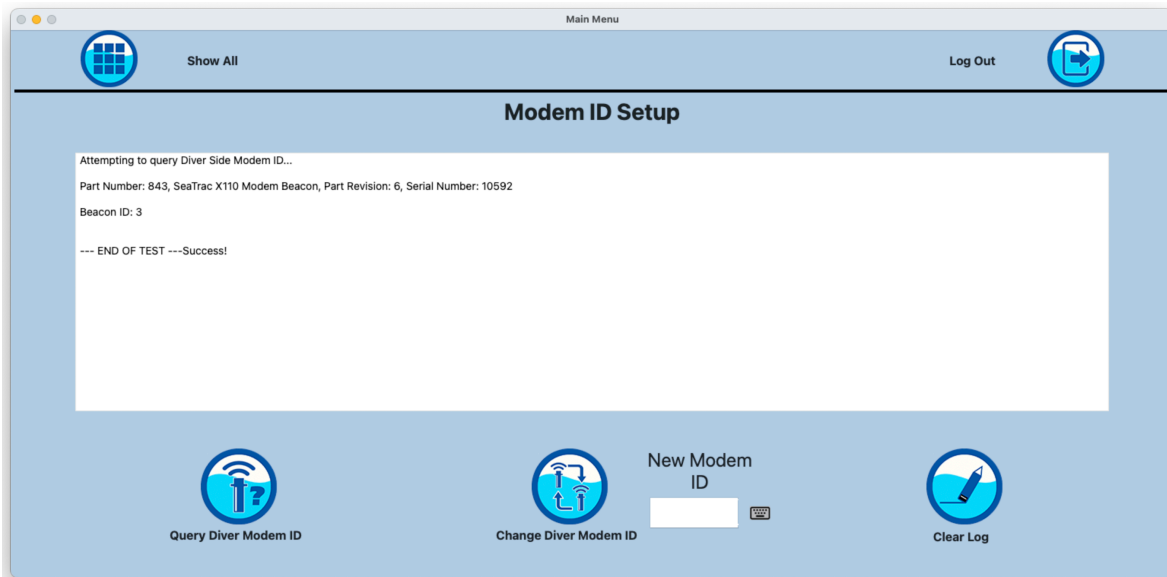


Figure 38: Modem ID Setup Screen



## Global Alarms

The Global Alarms screen (Figure 39) displays system-wide alarms which are organized into categories. A default set of global values is provided and can be enabled/disabled by checking/unchecking the box beside the particular alarm. Pressing the **Reset Global Alarms to Factory Defaults** button will restore the values to their default states. The units displayed can be toggled between U.S. (PSI, Feet, Fahrenheit) and Metric (Bar, Meters, Celsius) by clicking the **Toggle Units** button. Clicking the **OK** button will save the changes and the **Cancel** button will abort.

When saving new global alarm values, the software will scan all diver alarms to update any out-of-range values and display a dialog box with all divers that were adjusted.

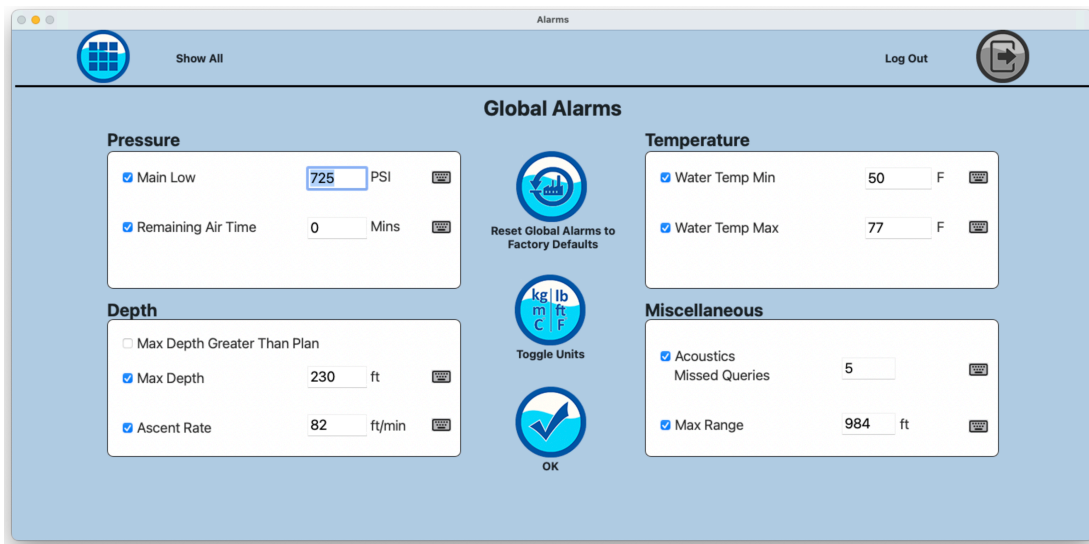


Figure 39: Global Alarms Screen

| Alarm                       | Default Value   | Triggered When                                 |
|-----------------------------|-----------------|--|
| Main Low                    | 725 psi         | Falls below value                              |
| Remaining Air Time          | 10 mins         | Falls below value                              |
| Max Depth Greater Than Plan | NO              | Diver depth exceeds plan depth                 |
| Max Depth                   | 164 ft.         | Exceeds value                                  |
| Ascent Rate                 | 59 ft./min      | The diver ascends too quickly and exceeds rate |
| Water Temp Min              | 50 F            | Water temperature falls below value            |
| Water Temp Max              | 77 F            | Water temperature exceeds value                |
| Acoustics                   | 5 transmissions | Fails to receive a number of responses         |
| Max Range                   | 984 ft.         | Exceeds value                                  |

## Destinations

The Manage Destinations Screen allows the Dive Masters to set up specific locations. Using the Shearwater® Petrel or NERD, the Dive Master can send a diver to a specific destination and the diver will receive range, bearing, and depth information to that location. New destinations can be created pre-mission or during the mission.

Clicking the **Destination** button will allow the Dive Masters to create, edit, and delete destinations. Existing destinations (up to six at a time) will be shown on the left side of the screen. Page up and page down buttons will become active with more than six destinations are available (Figure 40).

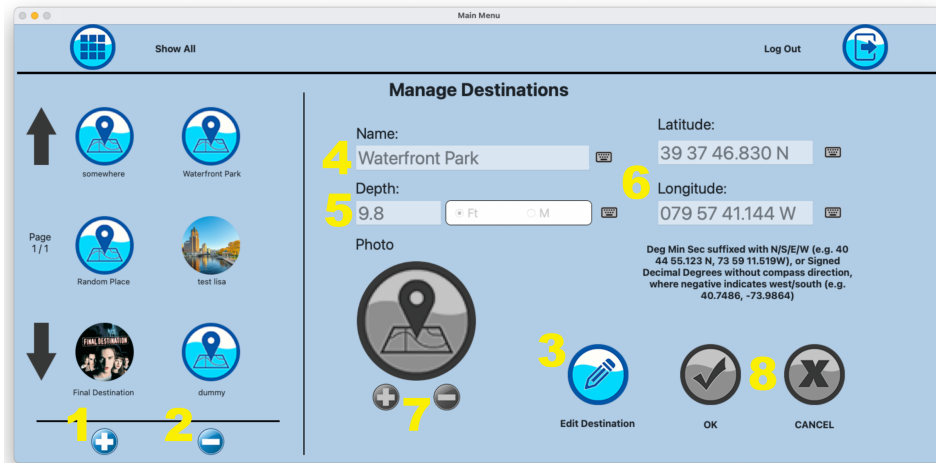


Figure 40: Destinations Screen

The Manage Destinations Screen has the following controls:

1. **Create Destination** – Allows the user to create a new destination.
2. **Delete Destination** – Allows the user to delete an existing destination. A confirmation box will be presented to confirm this action.
3. **Edit Destination** – Allows the user to edit an existing destination.
4. **Destination Name** – The name given to a destination.
5. **Depth** – The depth of the destination, click feet or meters.
6. **Latitude / Longitude** – Enter the coordinates of the destination (multiple formats are permitted).
7. **Choose / Clear Photo** – The Choose Photo button accesses any onboard/attached camera to take or choose photos (See **Choose Photo** for Details). The Clear Photo button clears the current image. The photo area also provides drag and drop support allowing JPEG and PNG files to be dropped on this location.
8. **OK / Cancel** – The **OK** button will save the changes and the **CANCEL** button will revert to the original data.

When clicking on any destination icon, the associated data will be displayed on the right side of the screen. The **Edit Destination** and **Delete Destination** buttons will also be activated. The destination data will be READ ONLY until the **Edit Destination** button is pressed. When the **Edit Destination** button is pressed, all fields can be edited, including the associated picture.



## Switch Dive Master

During extended dive operations, there may be a time when one Dive Master must leave and another one will take over. While a dive is currently in operation, the **Switch Diver Master** button will allow the current Dive Master to log out and another Dive Master to log in to continue monitoring the dive. When clicking this button, the current Dive Master's password must be entered first. Once correctly entered, the replacement Dive Master will have 60 seconds to log in. If the login does not occur in time, the current Dive Master will be logged back in as the dive continues to be monitored. This will ensure that both parties properly perform the handoff and that responsibility is passed on to the new Dive Master.

## Diagnostics

The Diagnostics screen allows the Dive Master to perform simple diagnostics to ensure modems are set up and communicating properly. Be sure that the Topside Modem is connected and the port has been chosen in the Communications section of the Configuration page.

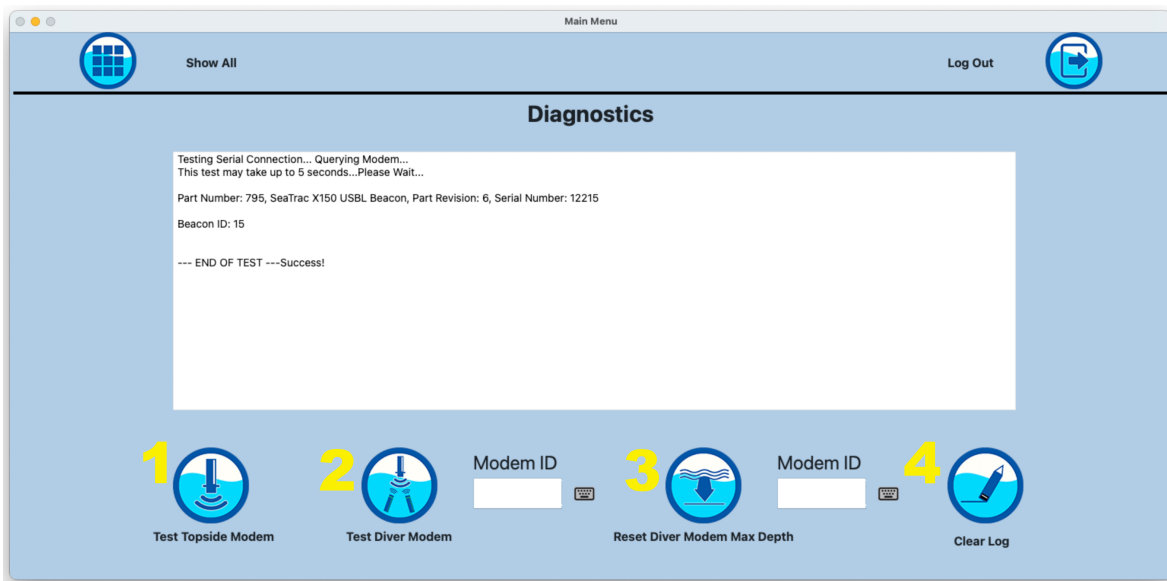


Figure 41: Diagnostics Screen

### 1. Test Topside Modem

This button will test the serial communications between the Topside Modem and the Diver6 computer. A successful test will display information about the Topside Modem. Some of this information may be required for warranty and repair situations. At the end of the test, a success or failure message will be displayed (Figure 41).

### 2. Test Diver Modem

Before running this test, ensure that the **Test Topside Modem** test has been run successfully. Enter the modem number to be tested and press the **Test Diver Modem** button. If communication is established with that modem, details from the modem are displayed. Otherwise, a failure message will be displayed.



In this case, the test may be performed again as necessary making sure the diver modem is powered on, has the correct modem ID, and is in range of the Topside Modem (Figure 41).

### 3. Reset Diver Modem Max Depth

Before running this test, ensure that the **Test Topside Modem** test has been run successfully. Enter the modem number to be tested and press the **Reset Diver Modem Max Depth** button. Results are displayed similarly to the Test Diver Modem results (Figure 41).

### 4. Clear Log

Clear log will clear the test output text area.

## Dive Log Maintenance

The Dive Log Maintenance screen allows the Dive Master to set up data export capabilities for use with external systems.

The Open Log Folder button will open the document log folder on the system computer. Each dive log folder is named in the format of DATE\_TIME, **Example: "Dive\_20201019\_085128"**. This will allow you to easily find the folder with the dive log information that you are looking to acquire. Inside each folder will be a number of different files pertaining to the given dive. GPX files, also known as GPS Exchange Format files are simply text files with geographic information such as waypoints, tracks, and routes saved in them. There will be one for each diver and one specific to the craft. Dive records for each diver and one combining all the divers (Full Dive Report) will be stored here as well in Portable Document Format (PDF). A Comma Separated Values (CSV) file contains all the processed data in a human-readable format that can be imported into Excel or some other software package. One final file starting with "rawCommaData" is useful for debugging and reviewing data transmissions. This file can be transferred to Azimuth should additional information or explanation be required. These dive log folders can be easily copied to external thumb drives or other media, emailed, or printed depending on the computer setup and connectivity.

Over time, a large number of dive logs may accumulate and take up an abundance of storage space. The Dive Log Maintenance screen (Figure 42) allows the Dive Master to delete files within specific time frames to help free up space. A confirmation box will be presented to ensure the Dive Master wants to delete the files.

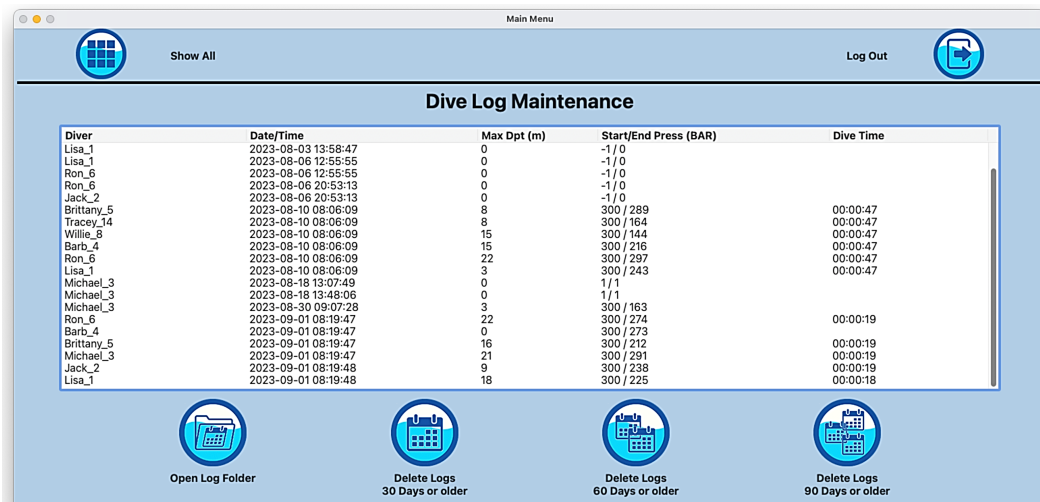


Figure 42: Dive Log Maintenance



## Dive Monitoring

The Dive Monitoring screens provide the Dive Master with detailed diver information, charts, dive team view (multiple diver information at once), alarms, dive tables (for reference or manual calculations/lookups), notes (to document events during the dive), and the ability to return to the dive plan screen (Figure 43).

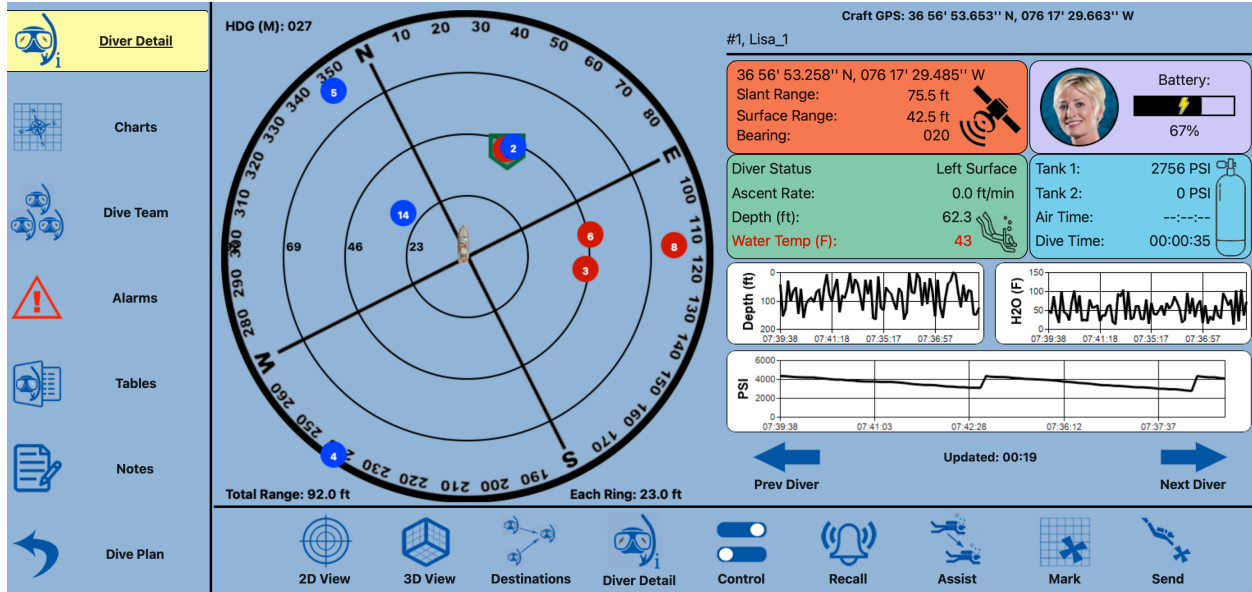


Figure 43: Dive Monitoring Screen

The main buttons on the left of the screen allow the Dive Master to see both detailed and summary information regarding the dive. At any time when input is required, these buttons will disappear and the bottom button area will change to a question with buttons to respond to the question. This question must be addressed before the main buttons return (Figure 44).

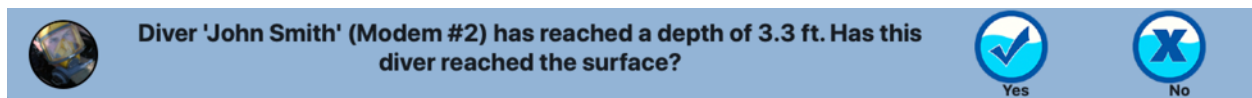


Figure 44: System Question Screen

With the basic Diver6 System, the only question that requires a response is “Has this diver reached the surface?” This will be asked after a diver has left the surface and returned to a depth of 2 meters (6.56 feet) or less. Depending on the dive, the Dive Master may answer “No” to this question if perhaps the diver returned to the surface to get a tool or swap out equipment.





## Diver Detail

The Diver Detail screen (Figure 45) provides a large view of data for a single diver. Clicking on the various gauges and graphs will toggle the units (Bar vs. PSI, Ft. vs. Meters, Fahrenheit vs. Celsius). The large blue arrows allow the Dive Master to traverse the list of all divers.

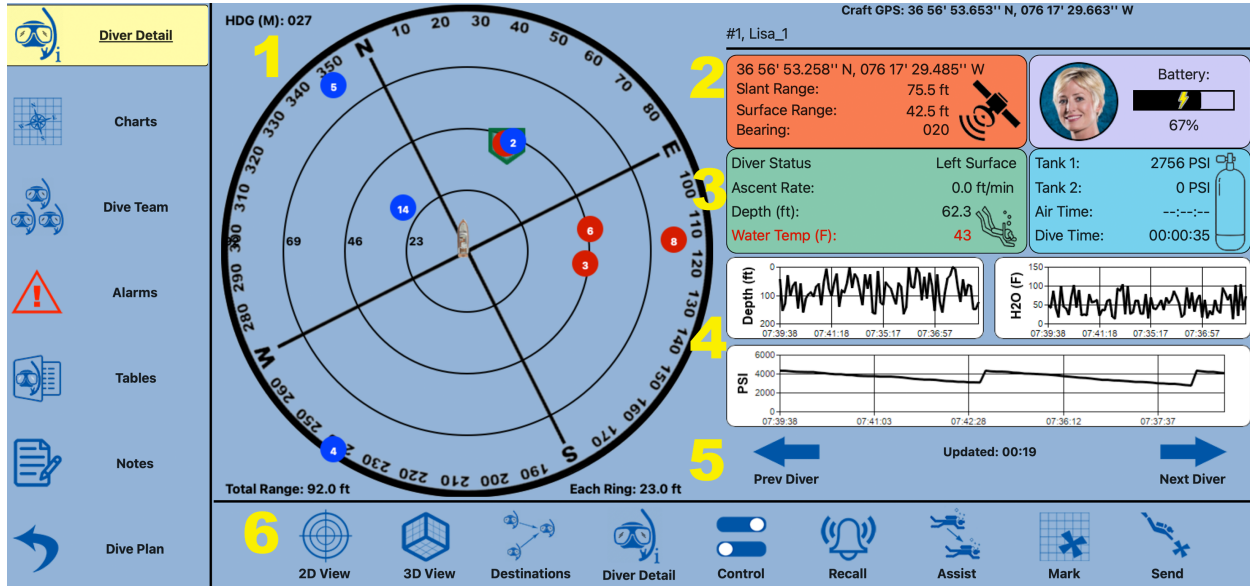


Figure 45: Diver Details Screen

## Data Descriptions

1. **Diver Position View** – Selected diver information is shown here. The selected diver will appear with a green badge surrounding the circle. **Diver icons appear as a blue-filled circle if there are no alarm conditions for that diver.** Otherwise, the icon will be a red-filled circle. This area also contains the craft heading and range rings. The range of the map is **dynamically adjusted** to include all divers in the view. In other words, as a diver gets further from the craft, the range of the map increases to ensure that all divers are shown on the screen. A textual explanation of the range rings is shown below the map
2. **Diver Location & Range** – Divemasters can observe the GPS location, Slant, and Surface range. Diver Ascent Rate, and Modem Battery Life are also observed here. Updated details are also available.
3. **Diver Environmentals** – Divemasters can observe the current diver position, tank pressure, water temp, and depth of the diver. The arrow on the diver profile shows the current azimuth of the diver.
4. **Histories** – Depth, Temp, and PSI histories can be observed
5. **Status and Selection** – The current location of the diver (on surface or left surface), dive time, and calculated air time can be observed here. The Dive Master can cycle through the divers by clicking on the left and right arrows.
6. **Views and Operation** – the dive master can change the view of the name of the diver and any additional status (e.g. recall, assisting, silent, etc.)



On all screens (except the Mapping screen), the Diver Name will consist of the name and any additional status text (Recall, Assisting #, Silent, etc.). This helps provide additional information regarding each diver. Note that the diver's name may be truncated to fit the status text on the screen.

The “Updated” text (*Updated: mm:ss*) appearing throughout the software provides information on the last time data was received from the particular diver modem.

The status of the diver (On Surface or Left Surface), dive time, and remaining air time are displayed below the graphs. The Dive Time is calculated as follows. When a diver descends to 2.0 meters or lower and remains there for 30 seconds or more, the Status field is updated to **Left Surface**. Dive Time will then show a value when the original descent reached 2.0 meters (thus starting at 30 seconds). The Dive Master can manually change this status (See Control Section).

The Air Time remaining is calculated using up to the last five minutes of pressure readings. A rate per minute is then calculated and this rate is used to determine how long it will take to reach 725 PSI (or 50 bar). If the tank pressure has remained constant over five minutes, the Air Time will read “INF” indicating no air has been used and there is an “infinite” time remaining. If the diver does not have a tank pressure sensor, the string “--:--:--” will be displayed.

When clicking on the Dive Time the Dive Master can toggle between the current dive time and cumulative dive time. The current dive time is the time between when a diver leaves the surface and returns to the surface. A diver can surface multiple times during a dive, and not get out of the water. The cumulative dive time is the total time the diver has been in the water for this dive.

Note that gauges and text will turn red (alarm color) if any alarm condition exists for that particular item.



## Views and Operations

The various views as well as options can be quickly changed using the buttons at the bottom of the screen.

### 2D View

The 2D top-down view provides the dive master with current craft heading and range rings. The range of the map is **dynamically adjusted** to include all divers in the view (Figure 46). In other words, as a diver gets further from the craft, the range of the map increases to ensure that all divers are shown on the screen. A textual explanation of the range rings is shown below the the map.

The magnetic heading provided by the Topside Modem allows for the overlay of the compass. The compass provides the Dive Master a quick view of the general direction of the craft and divers.

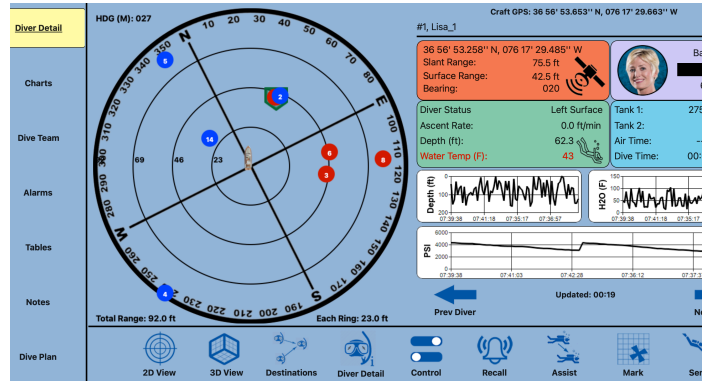


Figure 46: 2D and Range Ring Screen

### 3D View

Pressing the 3D button will change the dive map to a three-dimensional view (Figure 47). To rotate the 3D image, simply click on the image and drag your pointing device (mouse, pen, finger, etc.) around. Again, the Dive Master can cycle through all divers by clicking the left and right arrow keys (for previous and next diver selection) and the selected diver will appear surrounded by a green badge.

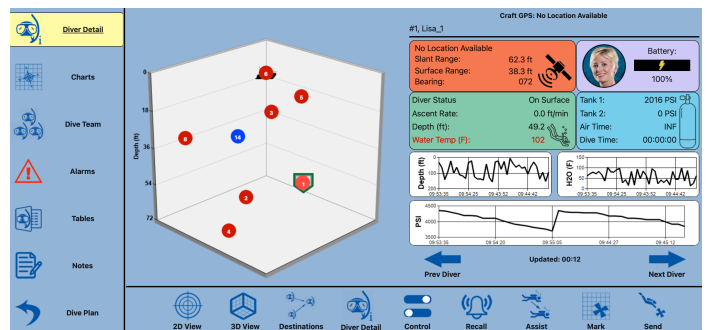


Figure 47: 3D Screen

### Destinations

The Destinations button will toggle the display of vectors for divers being recalled to the craft or those that are being sent to assist another diver (Shearwater® capability) (Figure 48). Also, it will show divers being sent to specific latitudes and longitudes marked as a yellow triangle.

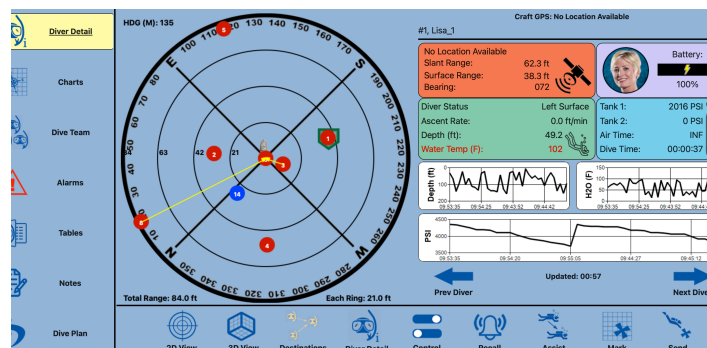


Figure 48: Destinations Screen

## Control

The **Control** button (Figure 49) will allow the Dive Master to control certain aspects of the current divers in the water.

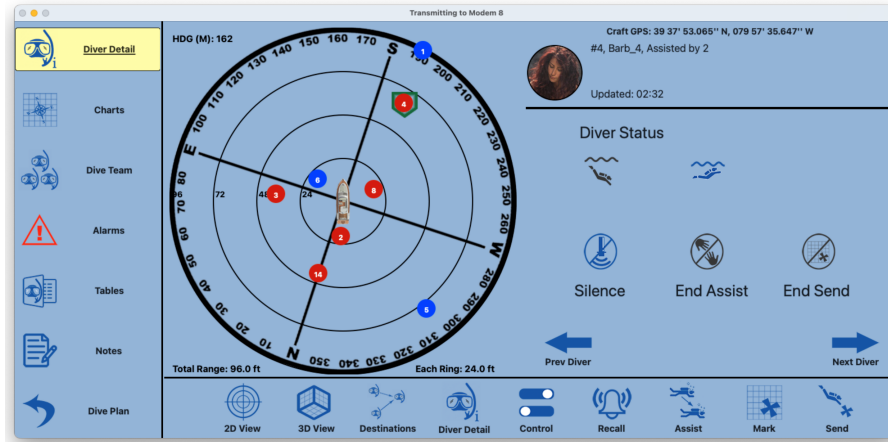


Figure 49: Diver Control Screen

**Diver Status** - Allows the user to manually modify the diver status (Left Surface, Reached Surface).

**Silence** - Silence the diver modem. Effectively, this stops the querying of the diver modem so that no acoustic signals are transmitted or received. This feature can be used in special circumstances where it may be critical for a diver not to be noticed. Once silenced, the modem may be enabled again by clicking the button that is now labeled “**Broadcast.**”

**End Assist** - End any assistance this diver is providing to another (only available with Shearwater® device). If this button is available, a confirmation dialog will be presented to ensure the Dive Master does want to end assistance.

**End Send** - End any sending of divers to a specific latitude and longitude. A confirmation dialog will be presented to ensure the Dive Master does want to end the operation.

### Audio and Visual Cues for Assist and Send

If the End Assist or End Send is selected, the modem will emit a one-second beep five times to alert the diver that the operation has been canceled. Then, the modem will stop beeping and any Shearwater® device will clear the operational message from the display.



## Recall

The **Recall** selection provides the ability to recall divers to the surface craft. The active divers in the water are displayed as seen in Figure 50. The dive master can select a diver from the list and recall that diver to the surface. The dive master can also recall ALL DIVERS to the surface. If a diver is being recalled, the word “Recall” will appear to the right of the diver’s ID. Once a diver has been selected to be recalled the system will pop up a confirmation window.

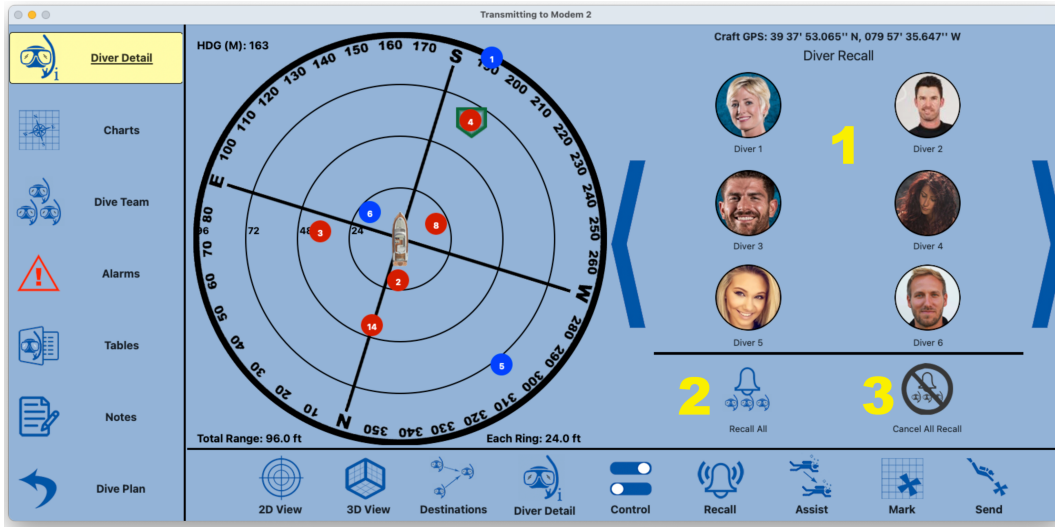


Figure 50: Diver Recall Screen

### Data Descriptions

1. **List of divers** – Select the diver to recall or cancel
2. **Recall All** – will recall all divers to the craft
3. **Cancel All Recall** – will cancel the recall message to all divers

### Audio and Visual Cues for Recall

The diver modem will emit three long beeps separated by one second of silence each time it receives a recall message. If the diver is using a Shearwater® device, a message to return to the craft with range and heading will be displayed (Figure 51). Following this, the Diver6 software will send messages so the Shearwater® device can display the updated range and heading to assist the diver in returning to the craft. If the recall is canceled, the modem will emit a one-second beep five times to alert the diver that the recall has been canceled. Then, the modem will stop beeping and any Shearwater® device will clear the recall message from the display.

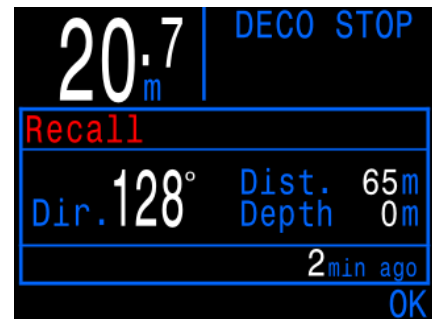


Figure 51: Recall Screen



## Assist

The **Assist** selection provides information to the Dive Master to help direct one diver to another.

If a diver needs assistance, the Dive Master can select that diver from the available divers shown (Figure 52). The large blue arrows allow the dive master to cycle through all available divers.

Once a diver has been selected for assistance, the screen will change to the view, as seen in Figure 53. The following information is provided:

- **Range** – distance to the diver in need
- **Heading** – direction to the diver in need
- **Depth Change** – the change in depth required to assist the diver in need.

Only divers that have a Shearwater® device are available to assist a diver. The Shearwater® provides directional information to direct the diver to the diver in need.

Once a diver is selected to assist, a confirmation dialog will be presented to ensure the Dive Master wants to initiate the assistance. If the Dive Master confirms, the Diver6 software will send messages so the Shearwater® device can display the range and heading to reach the diver requiring assistance (Figure 54).

When a Diver using a Shearwater® device is issued an assist message, the diver will have the option to accept the assist or cancel the assist. If accepted, the diver will be given a range, bearing, and depth to the diver that needs assistance. Upon arrival, the diver can notify the Dive Master that the target has been reached. Under certain circumstances, a diver may not be able to provide assistance and can cancel the task thus sending a message to the Dive Master.

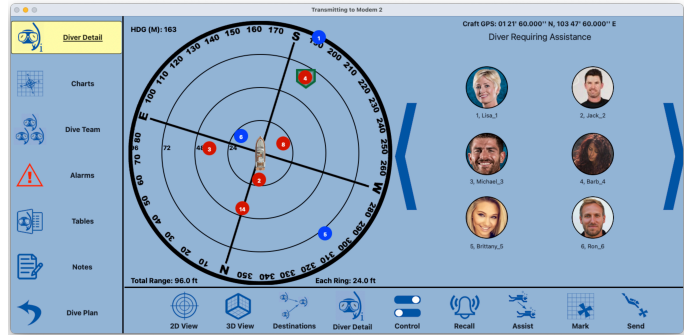


Figure 52: Diver Assist Screen

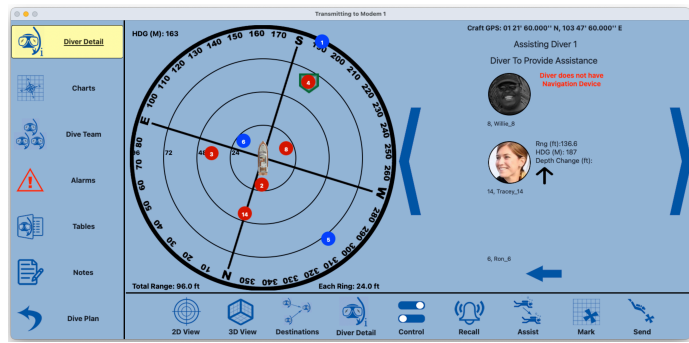


Figure 53: Diver Providing Assist Screen

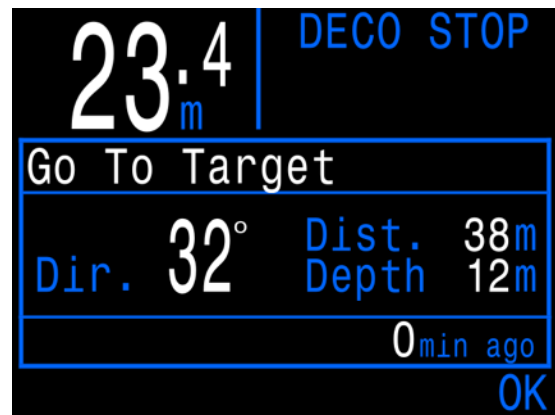


Figure 54: Go To Target Screen



## Mark

The Mark selection provides the ability to quickly add a selected diver's location (latitude, longitude, and depth) as a saved destination (Figure 55). When divers need to return to that location, the send diver function can be used. To save a diver's location, first, select the appropriate diver by either clicking on that diver on the 2D mapping area or by using the "Prev Diver" or "Next Diver" buttons. Then, enter a descriptive name in the "Marked Name" field and press the "Save" button. A confirmation dialog box will be displayed to ensure the Dive Master wants to save this destination.

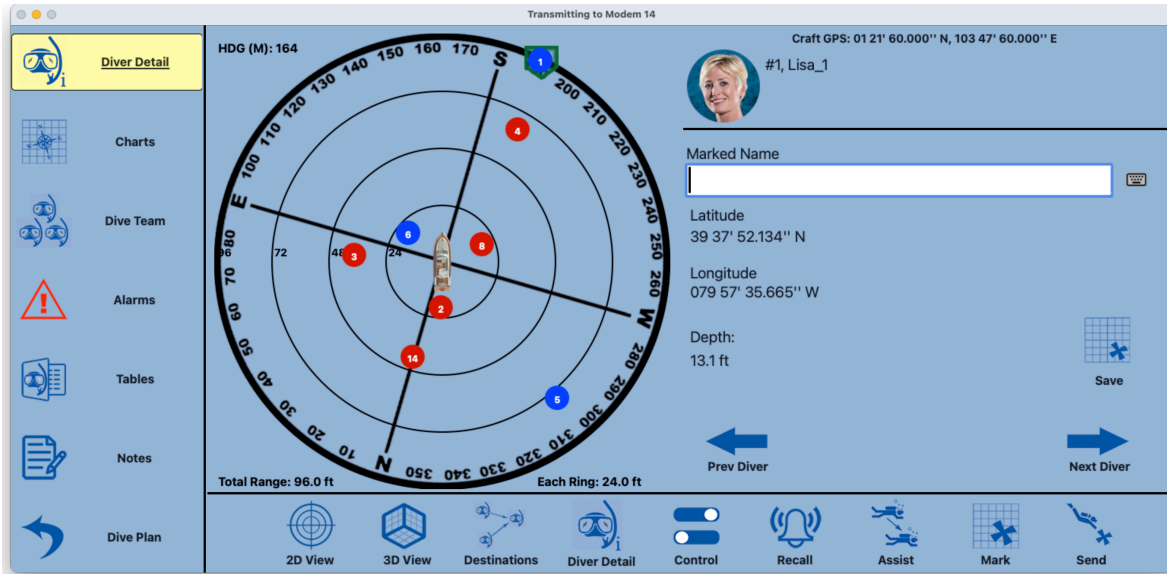


Figure 55: Mark Screen

## Send

The Send selection provides the ability to send a diver to a specific location (Figure 56). For example, if there is a place on the seafloor where a salvage team is working, the latitude and longitude can be recorded as a destination. When divers need to return to that location, the send diver function can be used.

**Note:** Only divers that have a Shearwater® device are available for Send functionality. The Shearwater® provides directional information to send the diver to the desired location.

Divers using a Shearwater® device will be highlighted for the operation. The Dive Master will select a valid diver to send. The system will then present destinations to which the diver can be sent (Figure 57).

The Dive Master can select a destination and the system will ask for confirmation. Once confirmed, the diver will be notified of the send operation.

When a Diver using a Shearwater® device is issued a send message, the diver will have the option to accept or cancel the send. If accepted, the diver will be given a range, bearing, and depth to the destination. Upon arrival, the diver can notify the Dive Master that the destination has been reached.

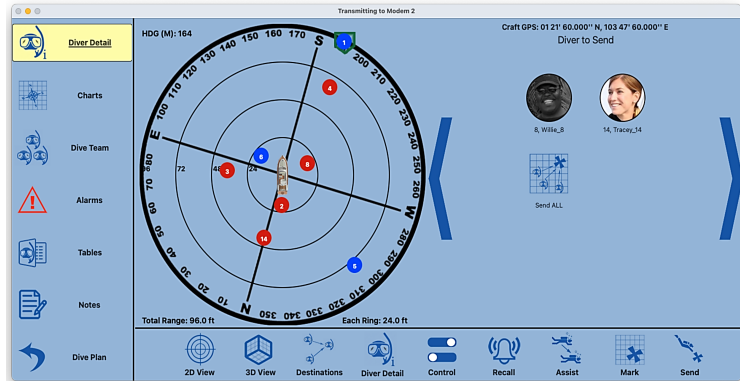


Figure 56: Diver to Send Screen

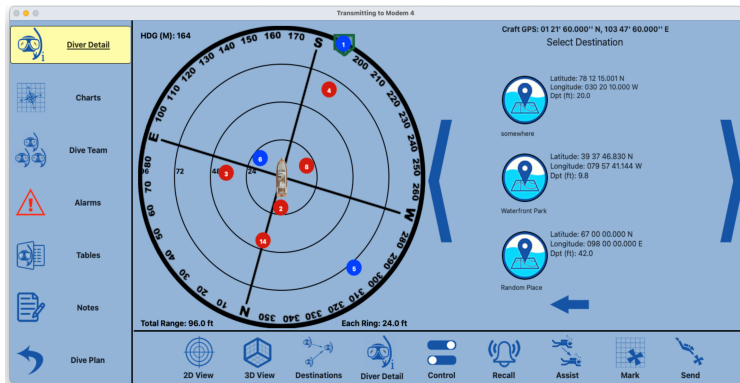


Figure 57: Destination to Send Diver Screen





## Charts

Pressing the Charts button will display ENC charts centered at the current location of the craft GPS. Diver markers will appear at their current GPS locations as well (Figure 58). To change the zoom level of the map, the Dive Master can click the plus or minus buttons in the upper left corner of the map. The blue menu buttons at the top provide the Dive Master with three options for lighting and three options for chart detail. For more information on loading charts and general chart maintenance, see the Chart Management Appendix.

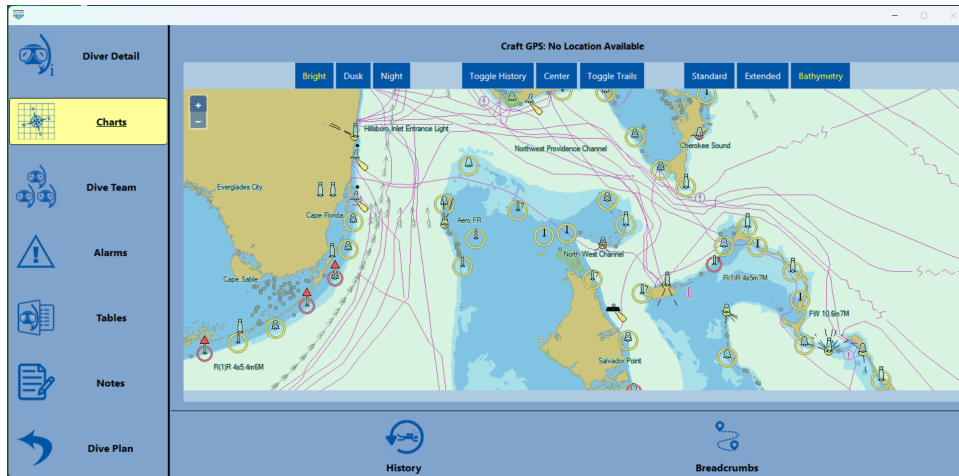


Figure 58: Mapping Screen

The History and Breadcrumbs buttons provide the capability to overlay historical dive data and activate current dive breadcrumb trails. These features indicate where divers have been on the current dive and where they have been on previous dives. The Dive Master can load multiple historical data files and then select in real-time which dives to view. With breadcrumbs, the Dive Master can select all or individual divers to view in real time.

The History button (Figure 59) allows the Dive Master to add historical dive data to the active dive. The “Load File” button will load historical dive data into the system. Dive Masters can load one or more data files for geographic analysis. Once loaded, the files can be selected for viewing by clicking the View checkbox. Files that are checked will be visible on the chart screen.

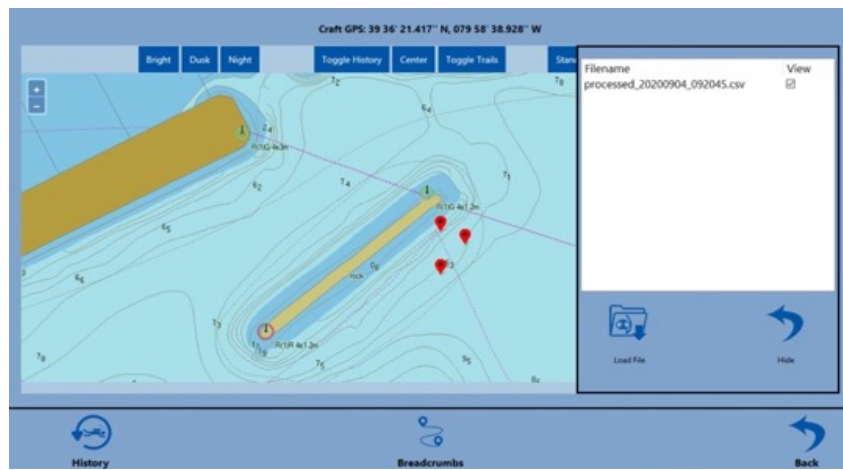


Figure 59: Historical Data Screen



The Breadcrumb button (Figure 60) allows the Dive Master to show the breadcrumb trail of any active diver. Each time diver location data is acquired, this data is logged. The data can be overlaid on the active dive in the chart screen. The breadcrumb data of any active diver can be viewed by selecting the View checkbox. In addition to selecting individual diver data, the “Show All” button will enable all breadcrumb data on all current divers. The “Hide All” button will disable viewing of breadcrumb data for all current divers.

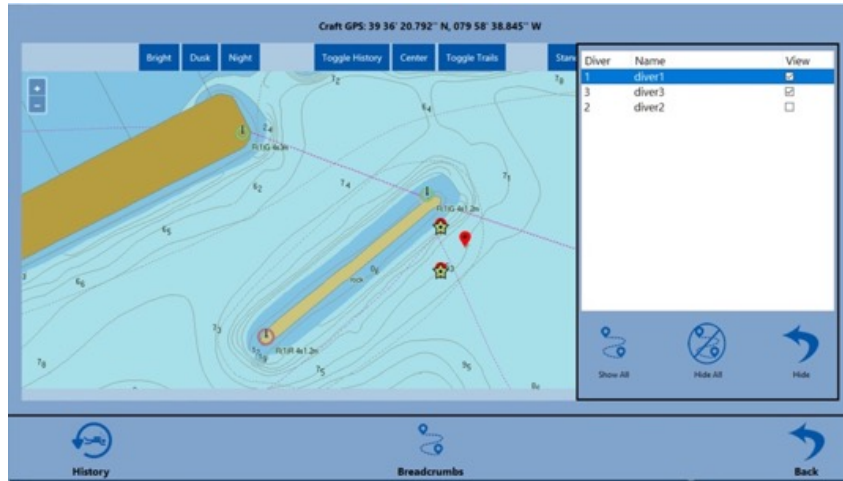


Figure 60: Breadcrumb Data Screen



## Dive Team

The **Dive Team** view will display summary information for up to six divers at once (Figure 61). The large left and right arrows will allow the Dive Master to traverse through divers six at a time. Clicking on one of the diver's photos will take you directly to the Diver Detail screen for that diver.

The Dive Team can display additional information regarding any external devices (e.g. Shearwater®). If a diver has a Shearwater® device, a small image of the associated device(s) (Petrel, NERD, pressure sensor) will appear. If the diver does not have any supported external device, a red "X" will appear in the box. The additional data provided by external devices can be viewed by clicking any of the diver's informational boxes. Clicking again will return to the original information box.

Dive team box borders will change color to indicate additional diver status updates as follows:

- **Black** – Normal operation/communication.
- **Green** – The border quickly flashes green when new data is obtained and then returns to black.
- **Yellow** – After five failed attempts to communicate, the border will turn yellow.
- **Red** – After six or more failed attempts to communicate, the border will turn red.

**NOTE: The icon under the diver image is the battery status of the Diver Modem. It is NOT the amount of air remaining in the tank.**

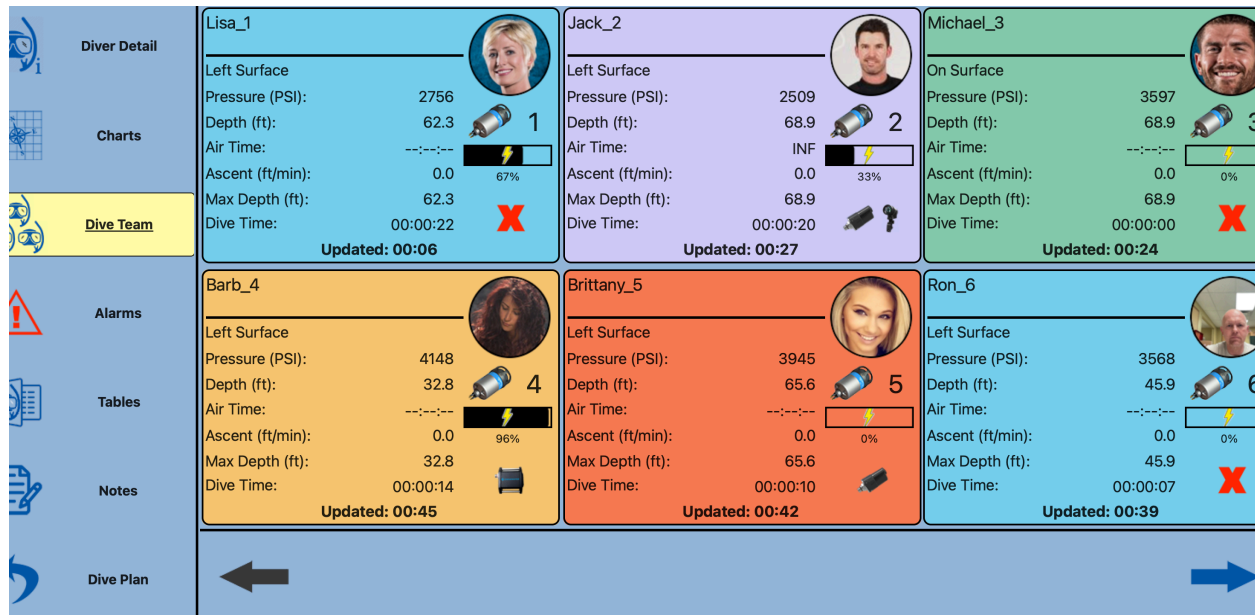


Figure 61: Dive Team Screen



## Alarms

When any alarm condition currently exists, the **Alarms** button will turn red to alert the Dive Master. In the case of the lost USB comms, the **Alarms** button will turn red with the “USB” indicator inside the icon. Ensure the Topside Modem is powered on and plugged into the Monitoring Computer properly.

The alarm screen displays (Figure 62) up to six divers at a time with the various alarm types. If an alarm exists for that diver, the circle beside the text is filled in red.

Using the large left and right arrow buttons will traverse the list of divers six at a time.

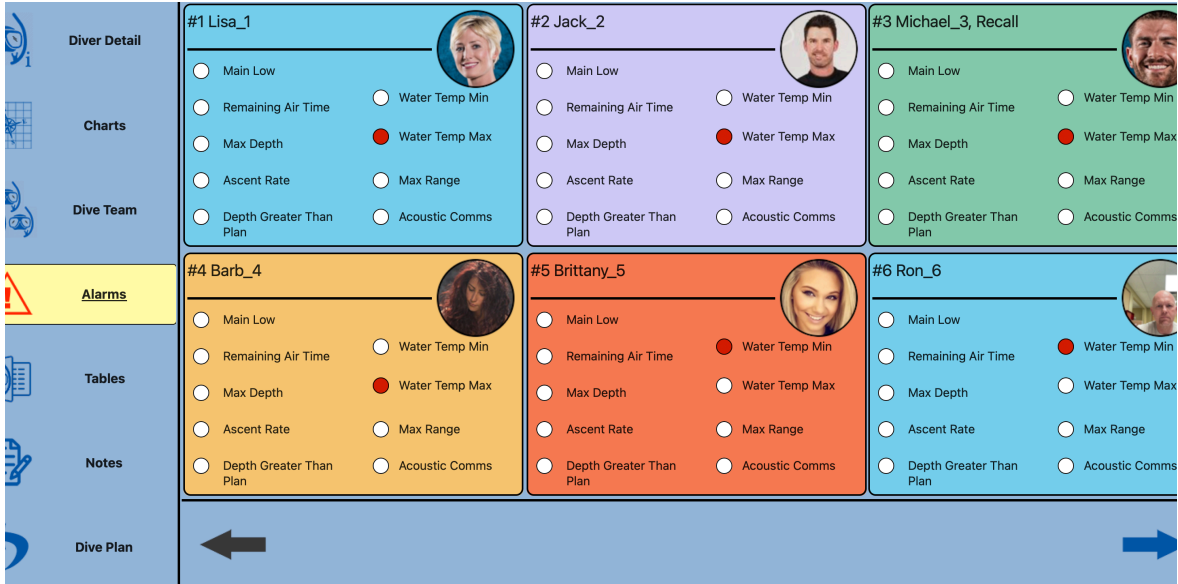


Figure 62: Diver Alarm Screen

### Alarm Details

See Alarm Details in the Global Alarms Section.



## Tables

The **Tables** button (Figure 63) provides various dive tables for quick reference and includes U.S. Navy, National Oceanic and Atmospheric Administration (NOAA), Professional Association of Diving Instructors (PADI), Buhlmann, and Defense and Civil Institute of Environmental Medicine (DCIEM). Clicking each main button for a dive table will display the corresponding dive table screen.

Once a table is chosen, a popup list at the top of the window allows the Dive Master to switch between the various sub-tables (Figure 64). When viewing the table, the user may scroll using the scroll bar on the right and bottom as required. Once a type of table (Navy, NOAA, PADI, etc.) is selected, the sub-tables are persistent meaning each time the **Tables** button is clicked, that same list of tables is available.

US Navy Tables (Dec 2016, Revision 7)

NDL and RG Designators for No-Deco Air Dives

**Table 9-7. No-Decompression Limits and Repetitive Group Designators for No-Decompression Air Dives.**

| Depth (fsw) | No-Stop Limit | Repetitive Group Designation |     |     |     |     |     |     |     |     |     |     |     |     |     |     |      |  |
|-------------|---------------|------------------------------|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|--|
|             |               | A                            | B   | C   | D   | E   | F   | G   | H   | I   | J   | K   | L   | M   | N   | O   | Z    |  |
| 10          | Unlimited     | 57                           | 101 | 158 | 245 | 426 | *   |     |     |     |     |     |     |     |     |     |      |  |
| 15          | Unlimited     | 36                           | 60  | 88  | 121 | 163 | 217 | 297 | 449 | *   |     |     |     |     |     |     |      |  |
| 20          | Unlimited     | 26                           | 43  | 61  | 82  | 106 | 133 | 165 | 205 | 256 | 330 | 461 | *   |     |     |     |      |  |
| 25          | 1102          | 20                           | 33  | 47  | 62  | 78  | 97  | 117 | 140 | 166 | 198 | 236 | 285 | 354 | 469 | 992 | 1102 |  |
| 30          | 371           | 17                           | 27  | 38  | 50  | 62  | 76  | 91  | 107 | 125 | 145 | 167 | 193 | 223 | 260 | 307 | 371  |  |
| 35          | 232           | 14                           | 23  | 32  | 42  | 52  | 63  | 74  | 87  | 100 | 115 | 131 | 148 | 168 | 190 | 215 | 232  |  |
| 40          | 163           | 12                           | 20  | 27  | 36  | 44  | 53  | 63  | 73  | 84  | 95  | 108 | 121 | 135 | 151 | 163 |      |  |

Figure 63: Dive Table Screen

US Navy Tables (Dec 2016, Revision 7)

NDL and RG Designators for No-Deco Air Dives

NDL and RG Designators for No-Deco Air Dives  
 RNT for Repetitive Air Dives  
 NDL and RG Designators for Shallow Water No-Deco Air Dives  
 RNT for Repetitive Shallow Water Air Dives  
 Air Decompression Table 30-70 FSW  
 Air Decompression Table 80-150 FSW  
 Air Decompression Table 160-300 FSW  
 Closed-Circuit Mixed-Gas UBA Deco Table .75 ata ppO2 N2 O2

**Table 9-7. No-Decompression Limits and Repetitive Group Designators for No-Decompression Air Dives.**

| Depth (fsw) | No-Stop Limit | Repetitive Group Designation |     |     |     |     |     |     |     |     |     |     |     |     |     |     |      |  |
|-------------|---------------|------------------------------|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|--|
|             |               | A                            | B   | C   | D   | E   | F   | G   | H   | I   | J   | K   | L   | M   | N   | O   | Z    |  |
| 10          | Unlimited     | 57                           | 101 | 158 | 245 | 426 | *   |     |     |     |     |     |     |     |     |     |      |  |
| 15          | Unlimited     | 36                           | 60  | 88  | 121 | 163 | 217 | 297 | 449 | *   |     |     |     |     |     |     |      |  |
| 20          | Unlimited     | 26                           | 43  | 61  | 82  | 106 | 133 | 165 | 205 | 256 | 330 | 461 | *   |     |     |     |      |  |
| 25          | 1102          | 20                           | 33  | 47  | 62  | 78  | 97  | 117 | 140 | 166 | 198 | 236 | 285 | 354 | 469 | 992 | 1102 |  |
| 30          | 371           | 17                           | 27  | 38  | 50  | 62  | 76  | 91  | 107 | 125 | 145 | 167 | 193 | 223 | 260 | 307 | 371  |  |
| 35          | 232           | 14                           | 23  | 32  | 42  | 52  | 63  | 74  | 87  | 100 | 115 | 131 | 148 | 168 | 190 | 215 | 232  |  |
| 40          | 163           | 12                           | 20  | 27  | 36  | 44  | 53  | 63  | 73  | 84  | 95  | 108 | 121 | 135 | 151 | 163 |      |  |

Figure 64: Selected Dive Tables Screen

## Notes

The **Notes** button (Figure 65) is used when a Dive Master wants to document an event during the dive. The left column provides a free-form text area for the Dive Master to enter notes. Pressing the **Submit** button below the text area will add the note to the note history with a date/time stamp. Observe only one line of the note will be shown but the entire note is saved. If the Dive Master wants to delete a previously entered note, he or she may select the note in the right list area and press the **Delete Selected Note** button. When the dive is completed, the recorded notes are included in the full dive report.

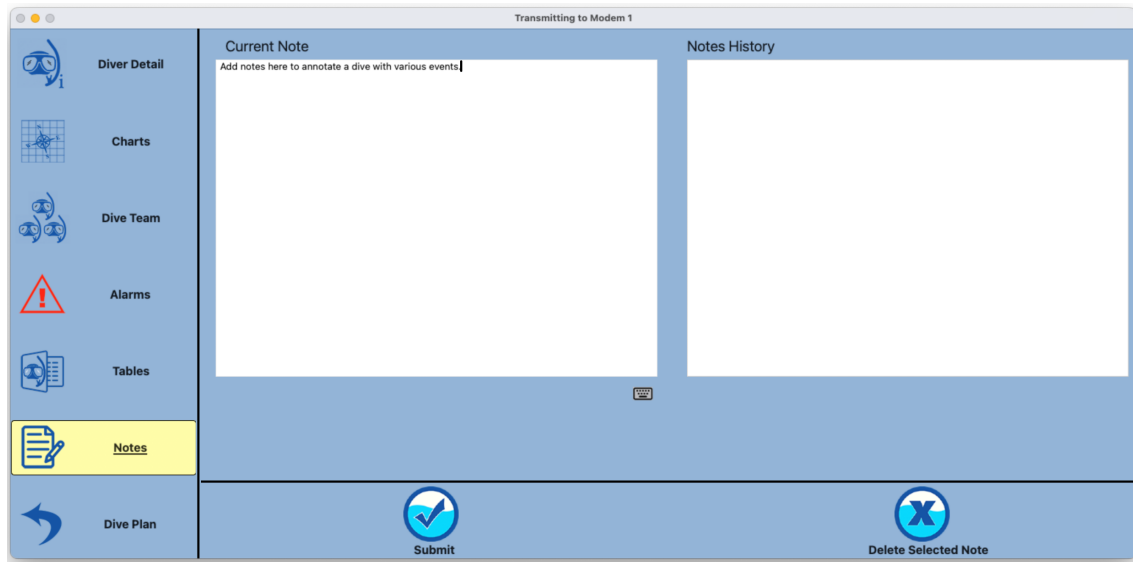


Figure 65: Notes Screen



## Additional Functionality

### Shearwater® Distress

A diver with a Shearwater® device may issue a Diver Distress message indicating that he or she is in trouble (Figure 66). This message will also appear in the question area on the screen to ensure the Dive Master sees and handles the situation effectively. When a diver issues the Diver Distress message, the modem will emit a Morse code SOS signal (3 short beeps, 3 long beeps, 3 short beeps). Each time the modem receives any communication from the Topside Modem, this SOS signal will be emitted. This can be helpful for another diver to hear the SOS call and head toward the diver in distress.

When the diver cancels the Diver Distress, the modem will stop beeping and a message will be sent to the Dive Master indicating the Diver Distress call is complete (Figure 67). The distress cancel messages will appear in the question area to ensure the Dive Master recognizes the situation change.

### Shearwater® Send Return Home

A diver with a Shearwater® device may issue a diver Send Return Home message indicating that he or she would like the directional information to the topside craft. When a diver issues this command, a message is sent to the Dive Master, and the issuing diver is placed in RECALL mode. In RECALL mode, the diver is provided with the range and bearing to the topside craft.

When the diver cancels the Send Return Home (Figure 68) a message is sent to the Dive Master. The diver will be taken out of RECALL mode and will no longer receive range and bearing to the topside craft. Normal operation will resume.

### Shearwater® Send Assist

A diver with a Shearwater® device may issue a Send Assist (Figure 69) message indicating that he or she needs assistance. This functionality is to be used in a non-threatening, non-lethal scenario. When a diver issues this command, the Dive Master is notified and can then direct the best available diver to the diver in need.

When the diver cancels the Send Assist the Dive Master is notified and can make the appropriate adjustments. Normal operation is resumed.



Figure 66: Distress Screen



Figure 67: Confirm Distress



Figure 68: Return Home



Figure 69: Send Assist



# Section 6: Maintenance

## Introduction

The Diver6 System has been designed for minimal maintenance. All materials on the Diver6 System have been carefully selected to minimize maintenance. Where possible the Diver6 System has been sealed to prevent any sensitive components from being exposed to the harsh marine environment.

## Routine Maintenance

In addition to the routine deployment tasks outlined in Section 4 of this manual, the following routine maintenance tasks should be performed:

## Weekly Maintenance Tasks

| Equipment           | No. | Weekly Maintenance Summary  |
|---------------------|-----|---|
| Diver Modem         | 6   | <ul style="list-style-type: none"><li>• Diver Modem Connector O-Ring:<ul style="list-style-type: none"><li>○ If the O-ring appears defective, please remove the O-ring on the Diver Modem using the plastic O-ring pick in the Tools &amp; Spares Kit.</li><li>○ Clean the O-ring groove with a solvent wipe provided in the Tools &amp; Spares Kit.</li><li>○ Apply a very thin layer of O-ring grease (Christo-Lube MCG111) to a new Diver Modem O-ring and install a new O-ring into the O-ring groove, both are provided in the Tools &amp; Spares Kit.</li></ul></li></ul> |
| Spares Checking     | 1   | <ul style="list-style-type: none"><li>• Check stocking levels for O-rings and grease. Re-order from Azimuth as necessary.</li></ul>   |
| Monitoring Computer | 1   | <ul style="list-style-type: none"><li>• It is suggested to fully back up the hard drive on the Diver6 System Monitoring Computer.</li></ul>   |





## Return to Factory Annual Maintenance

It is recommended that each Diver6 System is returned annually to the Azimuth factory for full annual maintenance.

| Equipment                        | No. | Annual Maintenance Summary   |
|----------------------------------|-----|--|
| Topside Modem                    | 1   | <ol style="list-style-type: none"><li>2. Firmware Upgrade</li><li>3. Housing Check: Disassemble and check internals, replace O-rings</li></ol>   |
| Diver Modem                      |     | <ul style="list-style-type: none"><li>• Firmware upgrade</li><li>• Inspect for physical damage, specifically to the depth sensor</li><li>• Visually inspect internal connections/wiring, PCB inspection</li><li>• Validate battery performance</li><li>• Charging system verification testing</li><li>• Check the depth and temperature sensor</li><li>• Unit performance testing with factory reference</li></ul> |
| Monitoring Computer              | 1   | <ul style="list-style-type: none"><li>• Inspect Tablet/Laptop Condition</li><li>• Reformat and install Operating System updates as needed</li><li>• Upgrade Software</li></ul>   |
| Topside Battery and Cable        | 1   | <ul style="list-style-type: none"><li>• Battery capacity verification</li><li>• Battery charger testing</li><li>• Clean and inspect for mechanical defects</li></ul>   |
| System-Level Performance Testing | 1   | <ul style="list-style-type: none"><li>• Full system-level performance testing of the entire Diver6 System against factory reference standards.</li></ul>   |
| Documentation                    | 1   | <ul style="list-style-type: none"><li>• Update user documentation</li><li>• Maintenance reporting comprising of:<ul style="list-style-type: none"><li>○ Condition Assessment</li><li>○ Recommendations for upgrade or repair of items</li></ul></li></ul>  |

Annual return to factory maintenance is a separate service contract to the purchase of the Diver6 Equipment. For details on the return to factory annual service price please contact your Diver6 System representative.



## Section 7: Troubleshooting

| Problem  | Possible Solutions   |
|--|--|
| Topside Modem not communicating with the software            | <ol style="list-style-type: none"><li>1. Confirm that the COMM ports are configured properly in the software. Run software diagnostic tests.</li><li>2. Confirm that all cables are properly connected.</li><li>3. Confirm that the Battery Unit is on.</li><li>4. Confirm that the battery is charged.</li></ol>  |
| Diver Modem not communicating                                | <ol style="list-style-type: none"><li>1. Confirm that the modem is properly configured in the software. Run software diagnostic tests.</li><li>2. Confirm that the modem is on.</li><li>3. Confirm that the modem is charged.</li></ol>  |
| Battery Unit will not turn on                                | <ol style="list-style-type: none"><li>1. Confirm that the battery is properly seated in the box.</li><li>2. Confirm that the battery is charged.</li></ol>   |
| USB will not connect   | <ol style="list-style-type: none"><li>1. Verify that your cabling is connected properly to the Topside Modem.</li><li>2. Verify that the Battery Unit is on and cabling is properly connected.</li><li>3. Verify that the battery is charged.</li><li>4. Verify that the USB driver is properly loaded.</li></ol>  |
| Tablet's internal GPS will not connect                       | <ol style="list-style-type: none"><li>1. Verify that the GPS settings are properly configured. Run software diagnostic tests.</li></ol>  |
| 3 <sup>rd</sup> party or external GPS will not connect       | <ol style="list-style-type: none"><li>1. Verify that the GPS settings are properly configured. Run software diagnostic tests.</li><li>2. Verify that your GPS is properly connected to your computer.</li><li>3. Verify that the GPS is on or NOT in sleep mode.</li><li>4. Verify that your GPS is communicating on the proper COMM channel. See your GPS manufacturer manual for details.</li><li>5. Verify that all software drivers from your GPS have been properly loaded. See your GPS manufacturer manual for details.</li></ol> |
| Tablet will not turn on                                      | <ol style="list-style-type: none"><li>1. Plug the unit into power source with the tablet charger. Possibly battery needs to be charged.</li><li>2. Push the power button to get the computer out of sleep mode.</li><li>3. Hold the power button for 5 or more seconds to shut the computer down, and restart the computer.</li></ol>  |
| Shearwater® NERD or Petrel will not connect/receive messages | <ol style="list-style-type: none"><li>1. Confirm that all your cabling is properly connected.</li><li>2. Ensure that you have the Diver6 firmware loaded on your device.</li><li>3. Refer to your Shearwater® manual for further troubleshooting.</li></ol>  |



Diver not getting pressure data from the Shearwater® pressure sensor

1. Confirm that your hose(s) is connected to the HP port on your regulator.
  - Confirm that your hose is properly connected to the Shearwater® pressure sensor.
  - Confirm that your pressure sensor is properly connected to the Diver Modem.



## CHART MANAGEMENT APPENDIX

The Diver6 Charts section features (Electronic Nautical Chart) ENC charts for viewing divers overlaid on a nautical chart. The charts are served locally on the Diver6 tablet and DO NOT require an internet connection to be viewed. The charting system supports S-57/63 charts.

The most up-to-date charts (U.S. charts) can be downloaded from the NOAA website: <http://www.charts.noaa.gov/ENCs/ENCs.shtml>. S-63 charts (international charts) can be purchased from our preferred vendor SiiTech ([www.siitech.com](http://www.siitech.com)).

Your system has been preloaded with all U.S. coastal charts. International customers will need to purchase charts for their area of operation.

## CHARTS OVERVIEW

The Charts section under the Options allows the Dive Master to view divers in the water with an ENC (S57/63) chart overlay. Charts provide the Dive Master with better diver situational awareness.

The Charts view (Figure 70) provides features for the Dive Master to easily manage the map and the divers. The Charts menu bar is composed of nine buttons.

- Bright:** Sets the charts with a day mode screen brightness.
- Dusk:** Sets the charts with a dusk mode screen brightness.
- Night:** Sets the charts with a night mode screen brightness.
- Toggle History:** Enables/Disables historical data view.
- Center:** Re-centers the chart based on the craft GPS (Tablet GPS).
- Toggle Trails:** Enables/Disables current diver breadcrumb trails.
- Standard:** Shows ENC view with the minimum amount of map detail.
- Extended:** Shows ENC view with more map details.
- Bathymetry:** Shows ENC view with most map details.

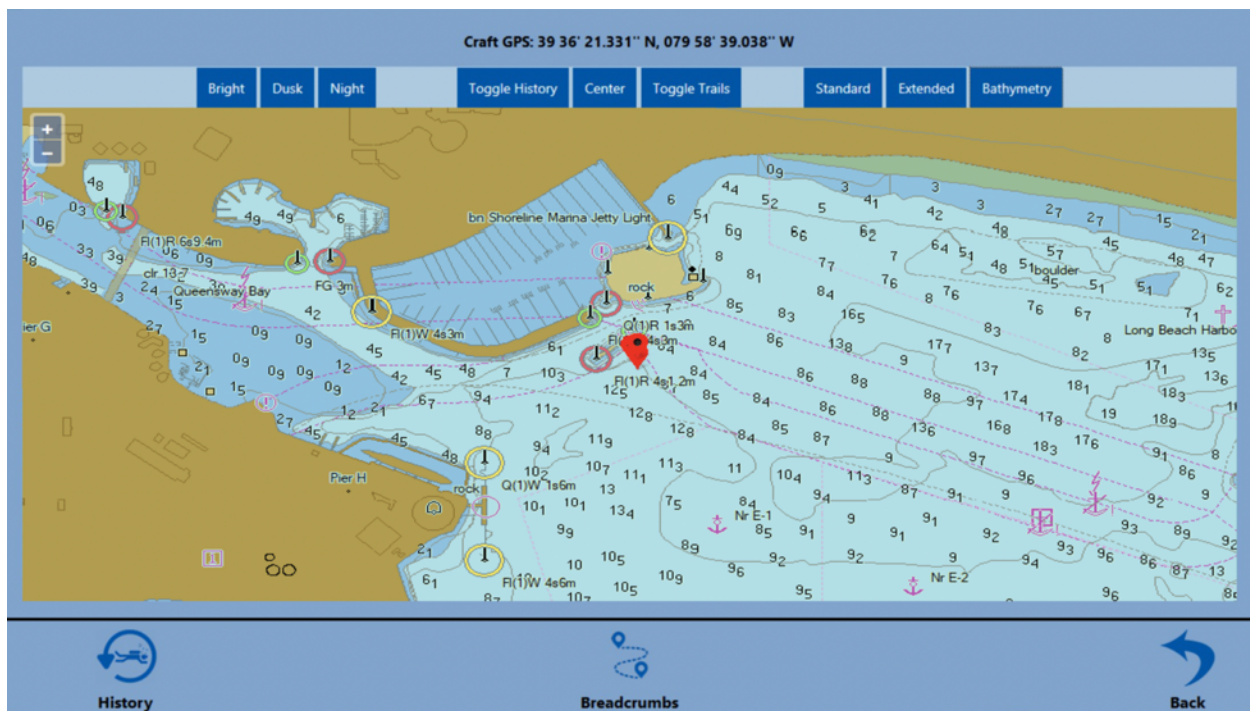


Figure 70: Charts View Screen



## Map Movement

The map can be moved by using the standard touch screen hand gestures. The pinch and pull commands will zoom the map in and out. You can also zoom using the plus and minus buttons in the upper left-hand corner. The map can also be dragged in any direction using the provided stylus or your index finger.

## Marker Identification

The markers on the screen are color-coded and consistent with the color scheme of markers throughout the Diver6 software.

**Blue Pin:** Represents a normal active diver.

**Red Pin:** Represents a diver with an alarm condition.

**White Pin:** Represents the craft (Ownship).

## Diver Information

Each diver on the screen has metadata for the Dive Master to view (Figure 71). By hovering the stylus over the diver marker or selecting a diver marker, a pop-up window will appear with information on that diver. This is a quick way for the Dive Master to get information on the diver in the water.

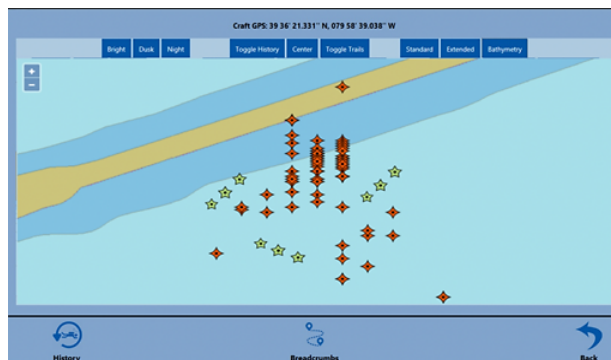


Figure 71: Charts Details Screen

## History and Trails

When the Dive Master loads historical data into the system or turns on the current dive breadcrumb trails for divers, that data can be viewed in real-time on the charts (Figure 72). The Toggle History and Toggle Trails buttons will show the diver data as an overlay on the charts. Historical data will appear as orange diamonds. Current dive breadcrumb trails will appear as green stars.

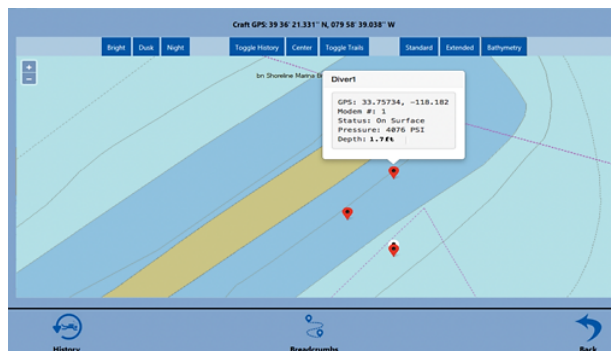


Figure 72: History and Trails Screen



## CHART SERVER

The Diver6 tablet is running an ENC chart server in the background. This server is locally hosted and does not require an internet connection for viewing and using the charts. Dive Masters will have access to their loaded charts anywhere in the world. The chart server is automatically started when the tablet boots up and no need for any user interaction.

### Gathering your Charts

#### U.S. Charts

The chart server will host S-57/S-63 charts. NOAA provides free charts for all U.S. States and Territories on their website.

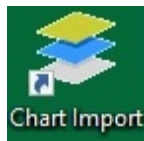
<http://www.charts.noaa.gov/ENCs/ENCs.shtml>

#### International Charts

International charts can be purchased and loaded into the system. We recommend using SiiTech. [www.SiiTech.com](http://www.SiiTech.com) to order your S-63 international charts.

### Loading your Charts (NOAA ENC)

1. Download your charts from NOAA: <http://www.charts.noaa.gov/ENCs/ENCs.shtml>
2. Unzip the downloaded file.
3. Click the Chart Import Icon on the Desktop OR locate the SiiTech folder in the Start menu and click the Chart Import Icon located there.



4. A window will appear waiting for your instruction (Figure 73).
  - a. In the “Chart Folder” text box, browse to the location of your recently downloaded charts.
  - b. In the GDB Folder text box – DO NOT CHANGE. This is the location of the chart database. If you make multiple database locations, you will have errors and missing charts on your machine. This folder location should remain UNCHANGED.
5. Click the Next button and your charts will be imported. Once the status bar has been filled, your charts have been added.

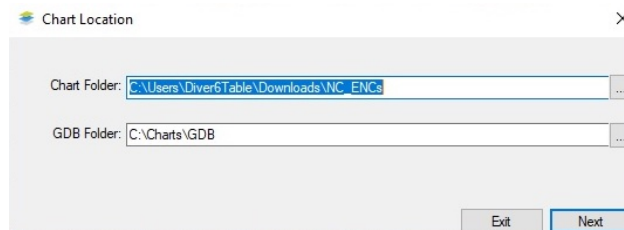


Figure 73: Chart Location

6. Reboot the machine.



## Loading your Charts (International S-63)

International charts purchased from SiiTech (our recommended provider) do not require the Chart Import tool. The charts are preconfigured by the manufacturer. Loading the charts requires a new Tile Server to be set up in the software.

**NOTE: We cannot guarantee or determine if international charts (S-63) not purchased from SiiTech will work properly in the ChartServer.**

### Setting up International Charts Tile Server

1. Download your charts and place them in your chart GDB directory. See (Figure 74) the example directory structure to the right.

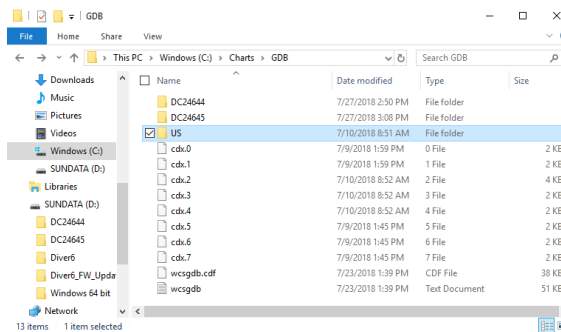


Figure 74: Chart Directory

2. Open the ChartServer Software. Click the EDIT menu and select “New Tile Server” (Figure 75).
3. When the “Tile Server Properties” window opens, give the server a unique name. It is recommended to name the server the geographic location you are loading.
4. Click the “Chart Options” button. The “ChartServer Option Properties” window will open.
5. Click the LOAD button on the ChartServer Options Properties Screen (Figure 76).
6. In the new window, locate the “.CDF” file within the directory tree of the S-63 charts that you are loading.

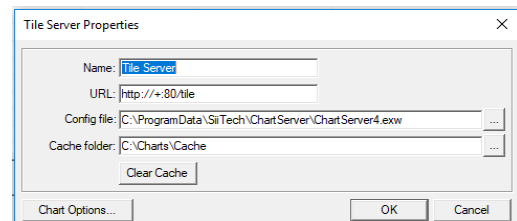


Figure 75: Tile Server Properties

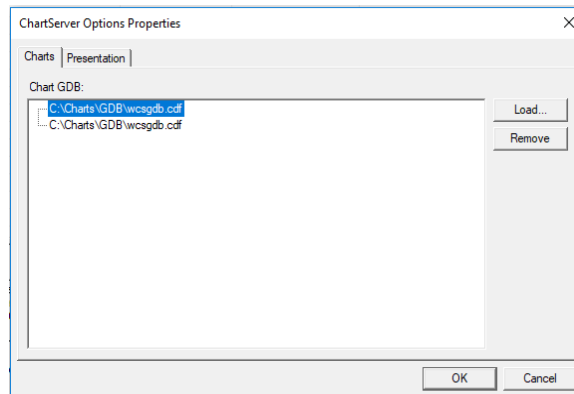


Figure 76: ChartServer Option Properties





7. Figure 77 is an example of the “.CDF” file. This file is the index file needed for S-63 charts to load in the Tile Server.
8. Click OK (Figure 77) when you are finished.
9. Reboot the machine.

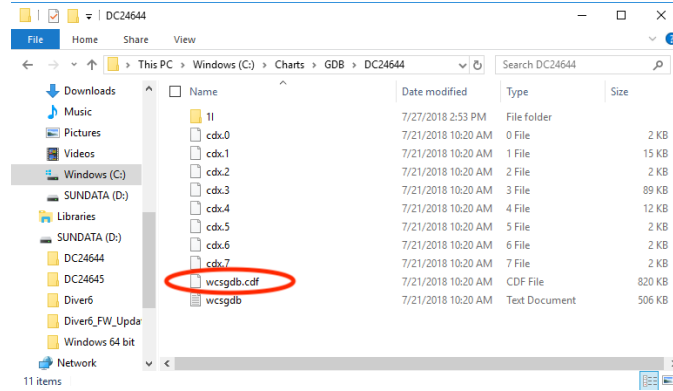


Figure 77: Chart Index File



## Hardware Device Firmware Maintenance

Some of the included hardware has user-updatable firmware. This allows the end-user to easily upgrade the firmware as it is released to obtain bug fixes, stability and reliability improvements, and new features. The two upgradeable hardware components are the DCM and the Shearwater® devices (Petrel and NERD). The most recent firmware files are downloadable from [www.diver6.com](http://www.diver6.com) under the Support menu.

### DCM

The DCM firmware can be updated using the supplied ICD-U80 programmer and the CCSLOAD programmer control software pre-installed on the tablet. Visit the downloads section from [www.ccsinfo.com](http://www.ccsinfo.com) for updates to the CCSLOAD software or USB drivers. To update the DCM firmware, do the following:

1. Download the newest DCM firmware file from the Diver6 website.
2. Run the CCSLOAD program and select the “Production” tab (Figure 78).
3. Ensure that the “Supply Power” checkbox is checked.
4. Click the Set Directory button and locate the directory with the downloaded firmware file. Select the “OK” button to continue.
5. If there is more than one firmware file in this location, ensure the correct one is selected from the list.
6. Confirm all hardware is properly connected (USB cable, ICD-U80, Tag-Connect.com cable to DCM). Note that you will have to apply slight pressure to push the Tag-Connect.com cable into the DCM port and hold in until programmed (Figure 79).
7. Press the “Start” button and the programming should commence.

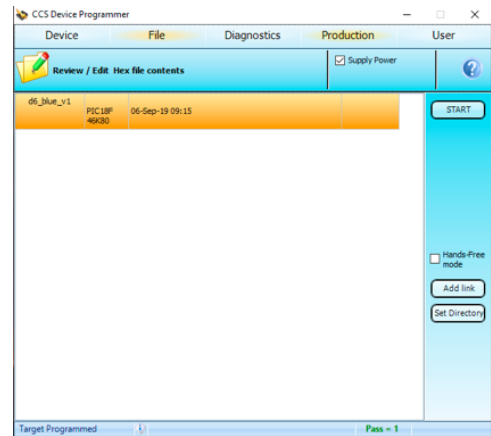


Figure 78: CCS Programming Software



Figure 79: Firmware Upgrade Port



## Shearwater® Devices

The Shearwater® devices (Petrel and NERD) can be upgraded using a Bluetooth connection and the pre-installed Shearwater® Desktop software. Visit the Support & Downloads section from [www.shearwater.com](http://www.shearwater.com) for updates to the Shearwater® Desktop software or use the “Check for Updates” item from the Help menu within the software.

To update the Shearwater® firmware, do the following:

1. Download the corresponding Shearwater® firmware file (ATN or Shearwater+ version) from the Diver6 website.
2. Simply double-click on the firmware file and the Shearwater® Desktop software should automatically run and present you with the “Update Firmware” screen (Figure 80)
3. Initialize Bluetooth on the dive computer and make sure it is in range of your computer.
4. Press the “Start” button on the software and once connected, the update should commence.

Note that this may take several attempts if the update does not complete the first time.

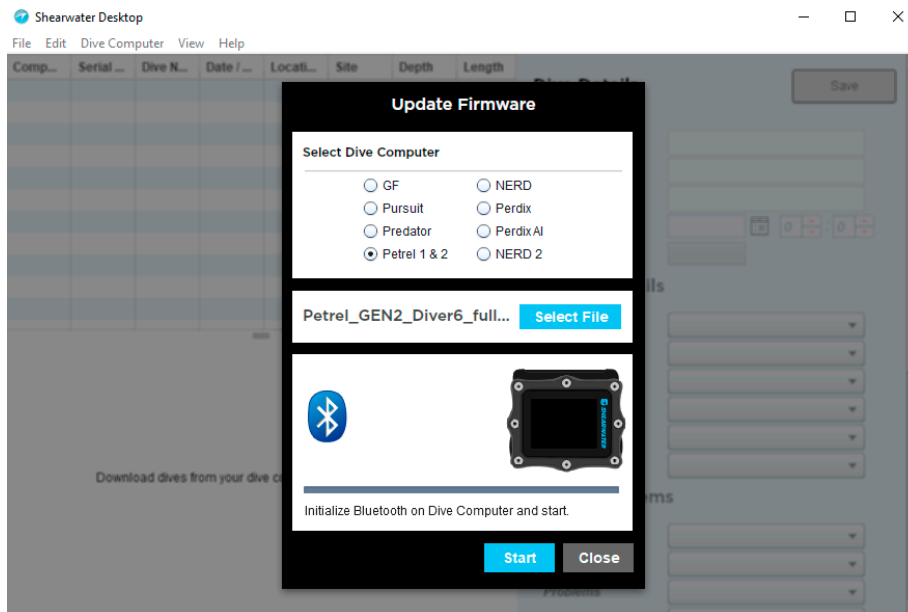


Figure 80: Shearwater® Update Screen